

# Completeness Masks and Galaxy Clustering in SAS2

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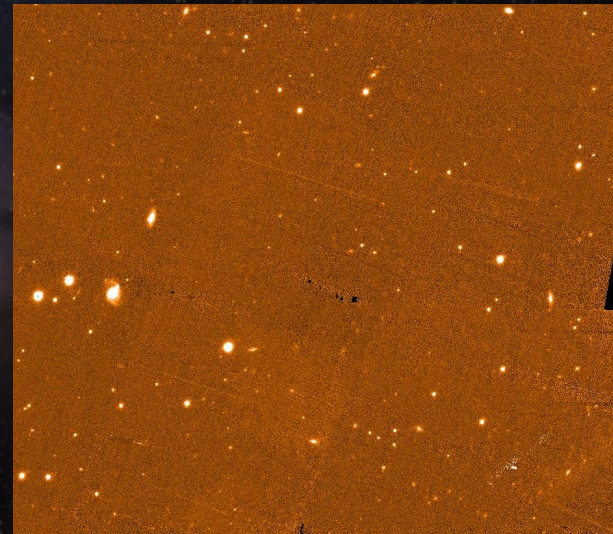
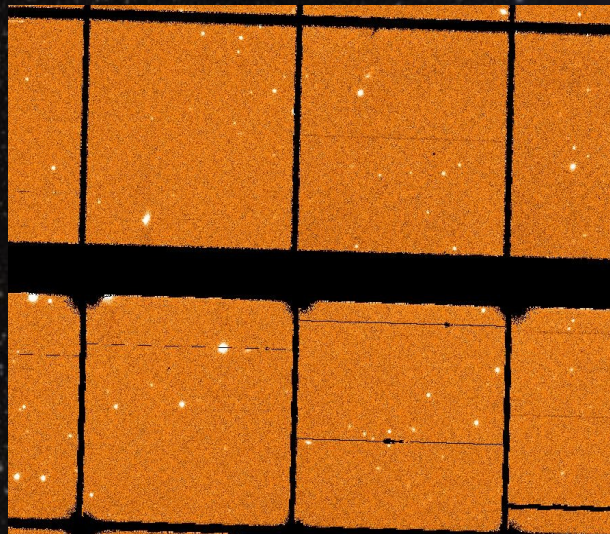
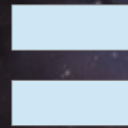
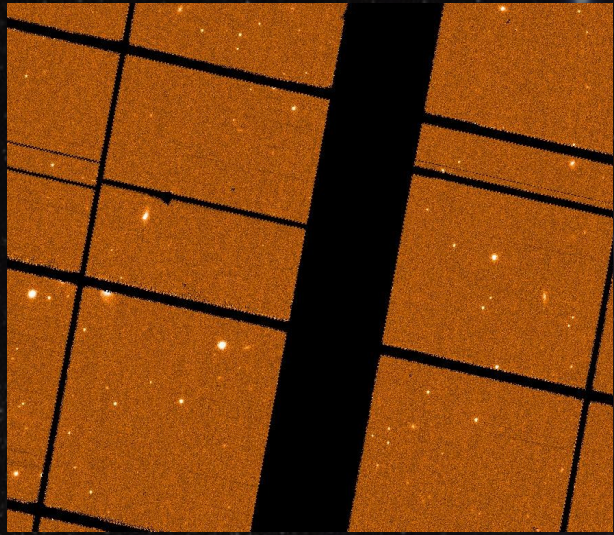
*With Shaun Cole, Nigel Metcalfe,  
Peter Draper, Peder Norberg &  
the PS1 team*



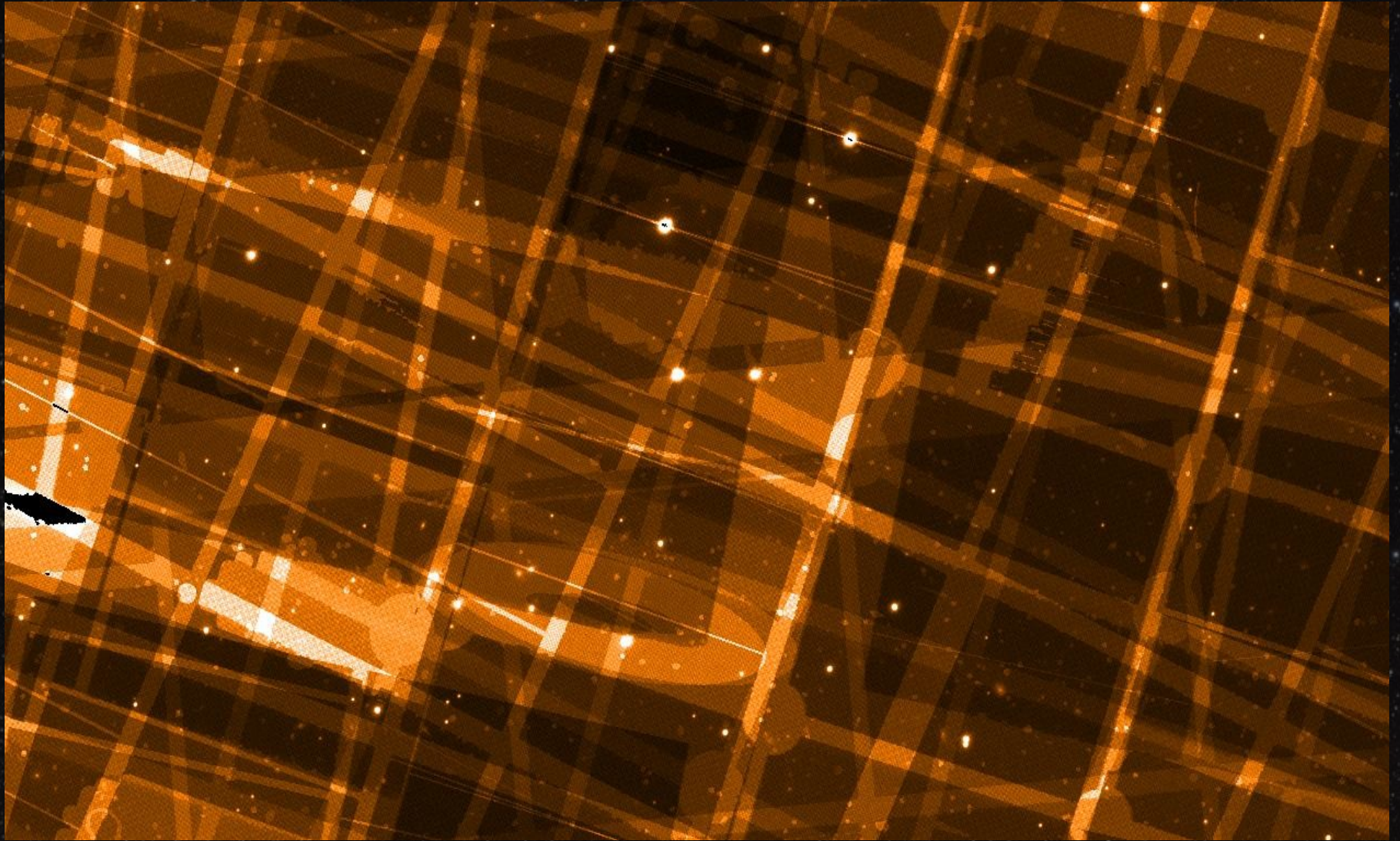
# Outline

- Already seen technique we used to star/galaxy separate – now need angular masks
- Spatially varying depth and variance maps
- Producing masks & 'primary resolution' problem
- Bright star mask
- Correcting for spatially varying depth
- Results

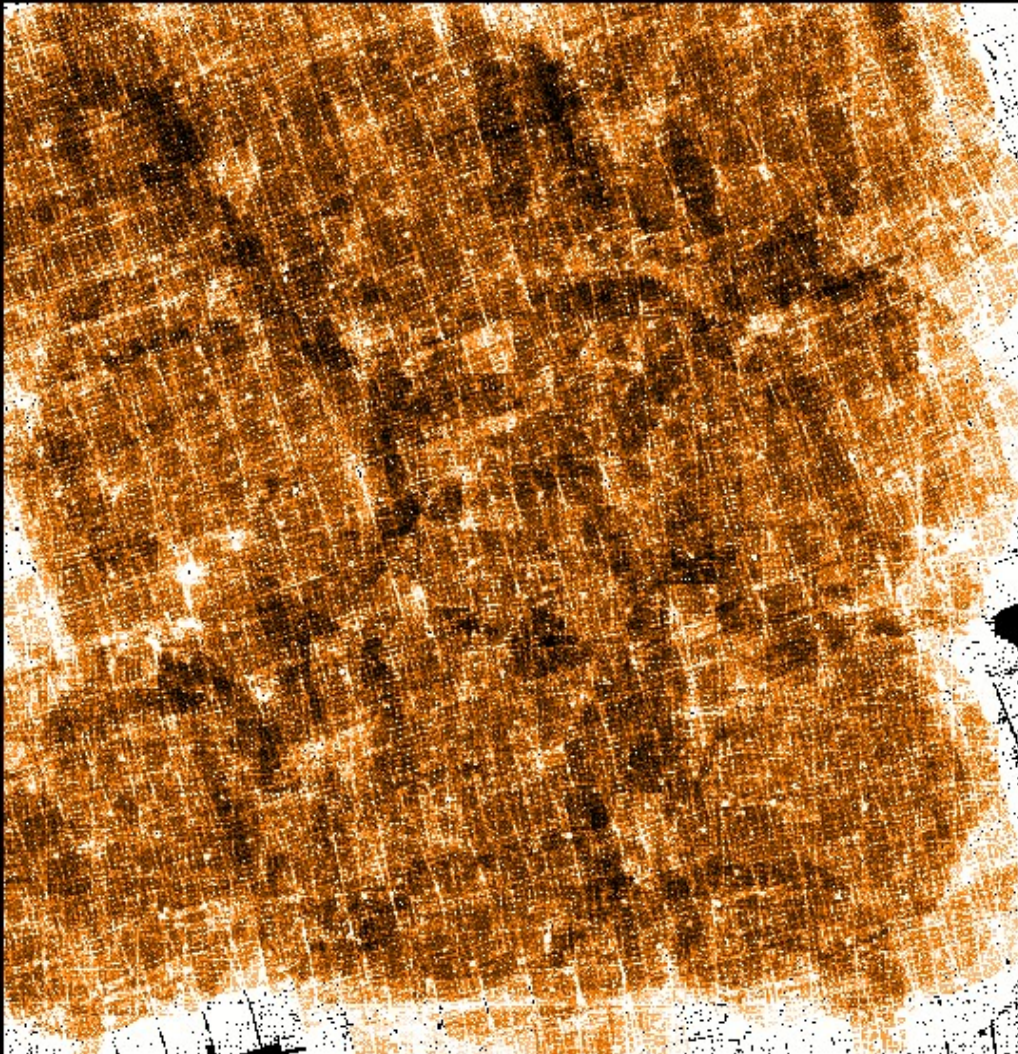
# Stacking



# Variance Maps

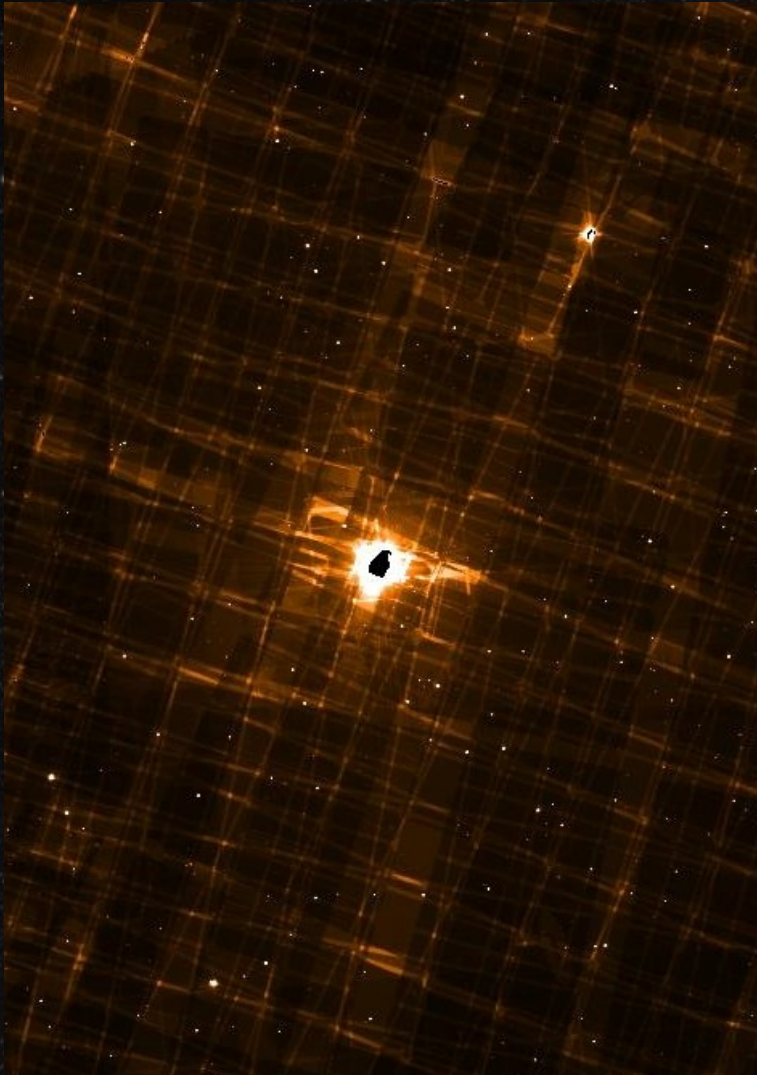


# Binning and Primary Resolution



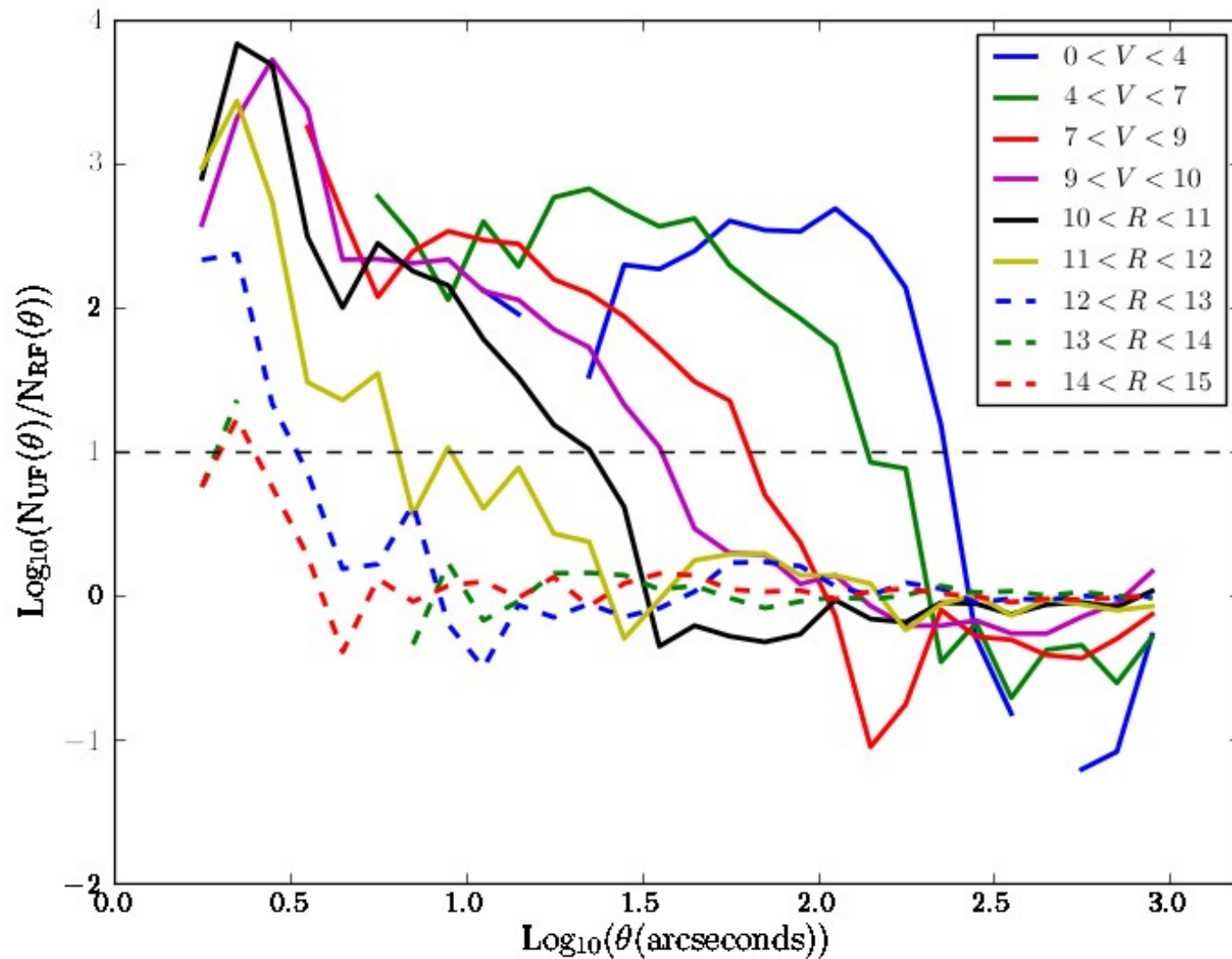
- Native pixel scale prohibitively large to work with across the full sky
- Skycells overlap, overlapping regions don't always contain the same pixels
- Need a lower resolution unique mask

# Bright Star Mask

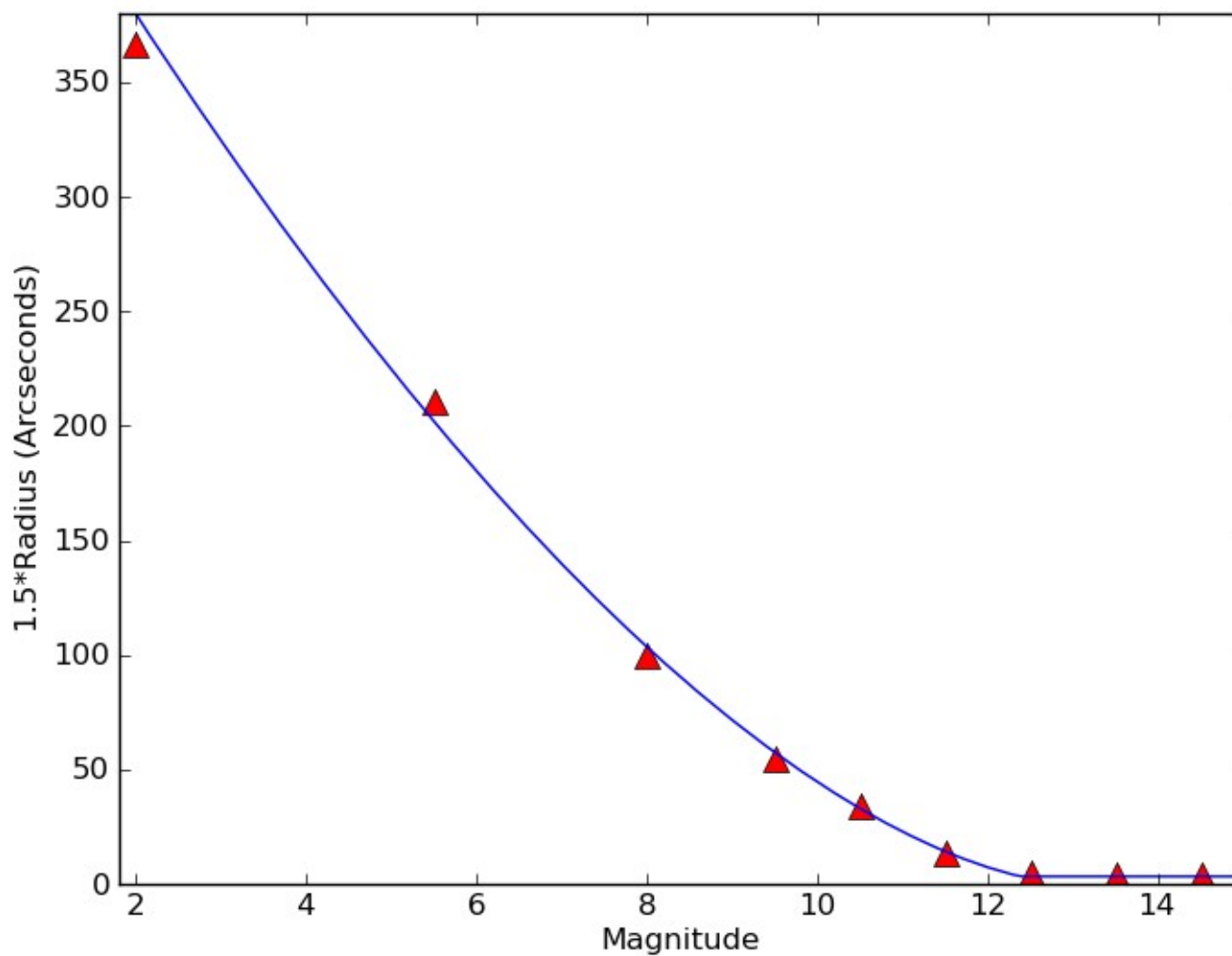


- Bright stars cause false positives
- Need to mask them
- Statistical approach to deciding mask sizes
- UCAC4.0 photometry for bright stars
- Identify candidate false positives by g & r matching

# Bright Star Mask

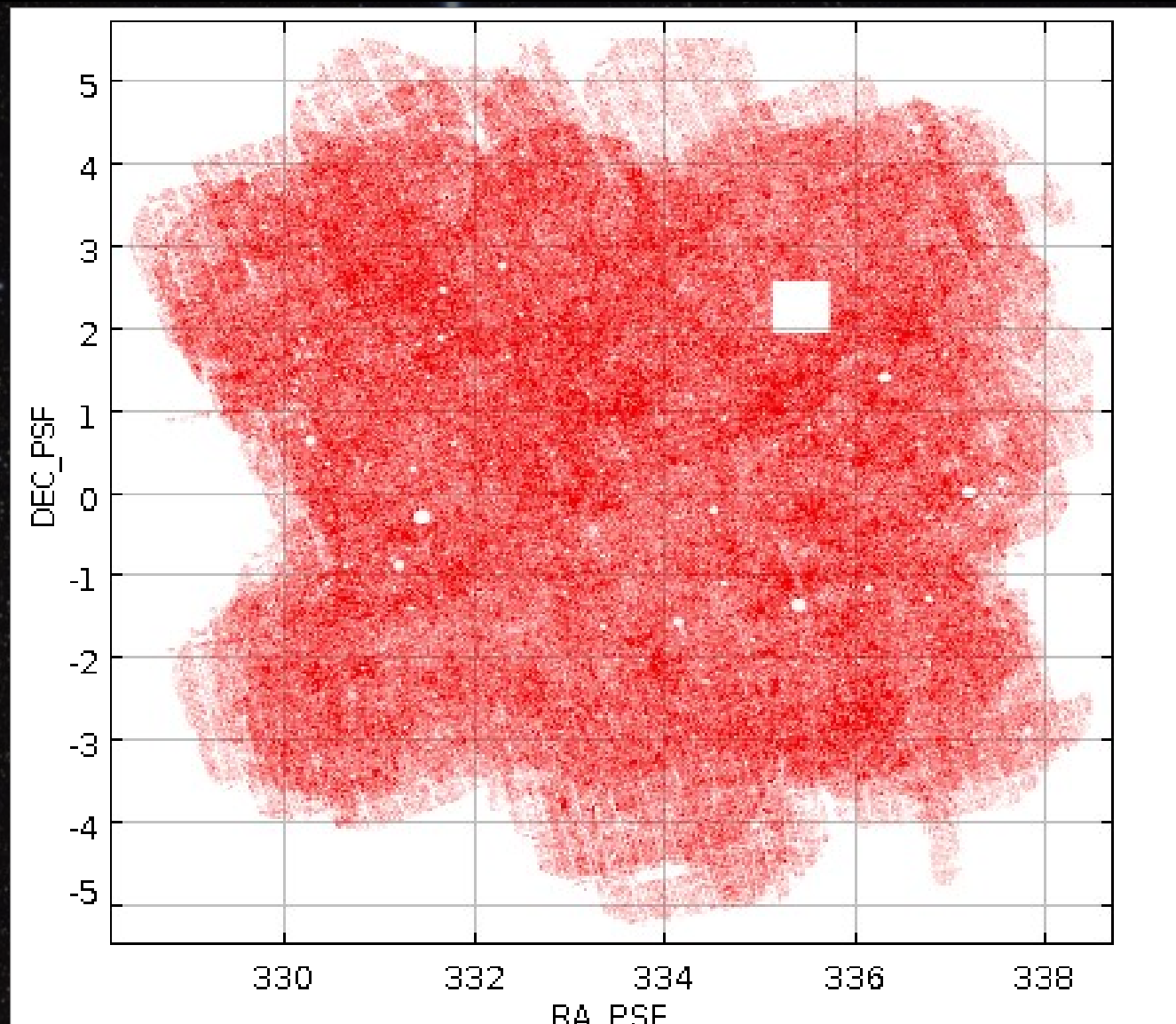


# Bright Star Mask

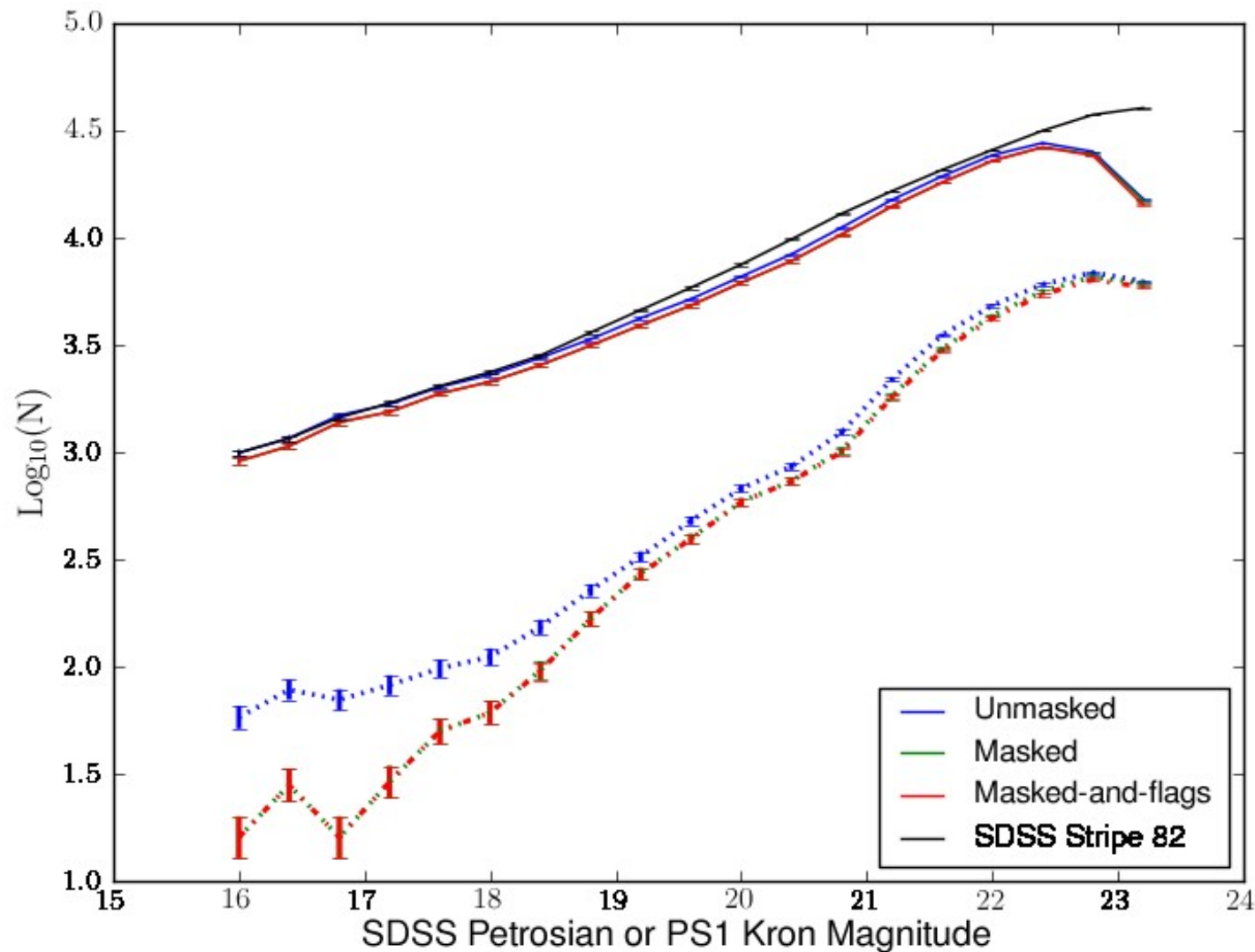




# The Mask



# Effect of Masking



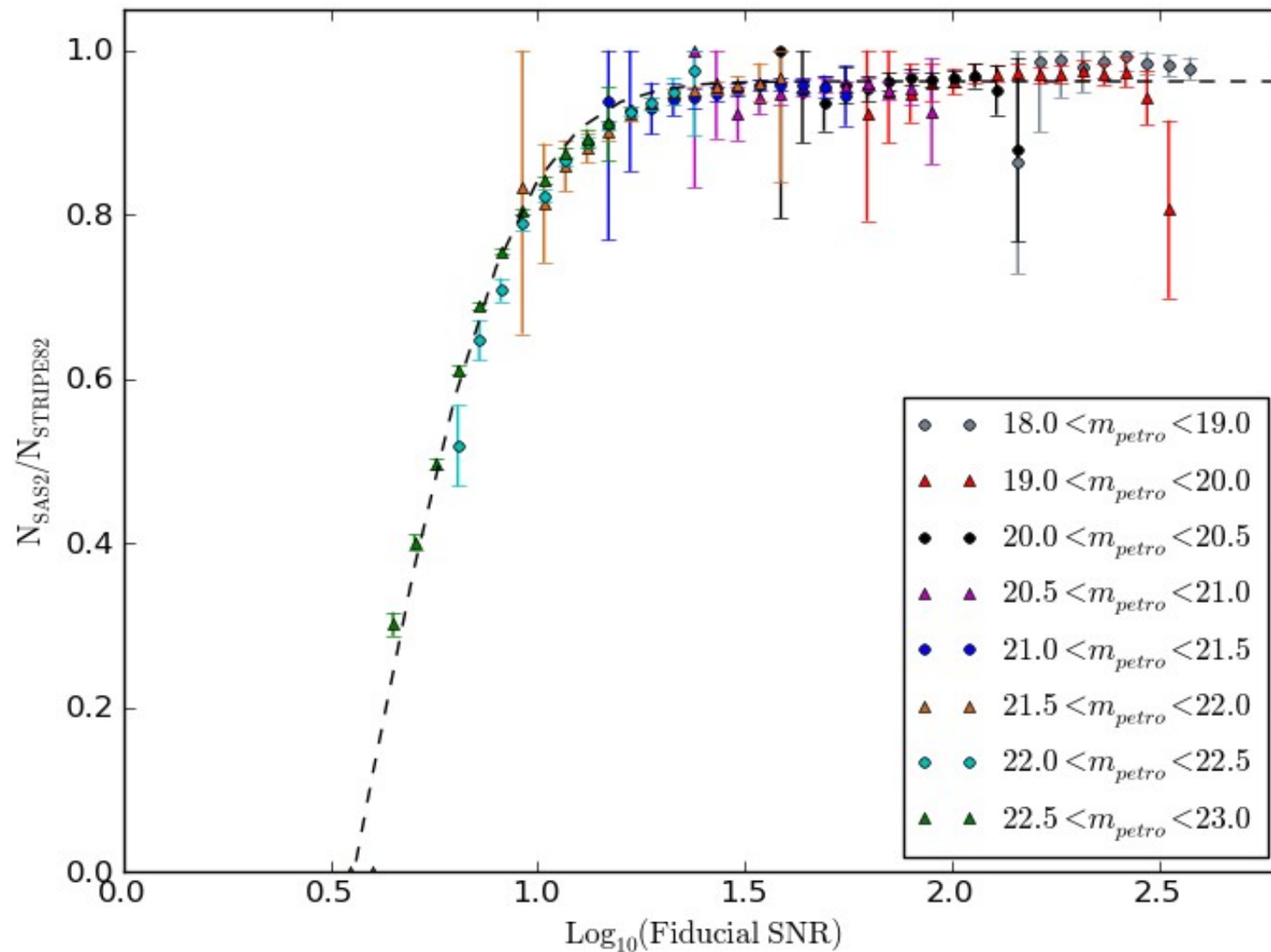
# Spatially Varying Depth

- Can't use magnitude to assess detection probability as depth varies across the sky
- Instead adopt a simplified measure of SNR

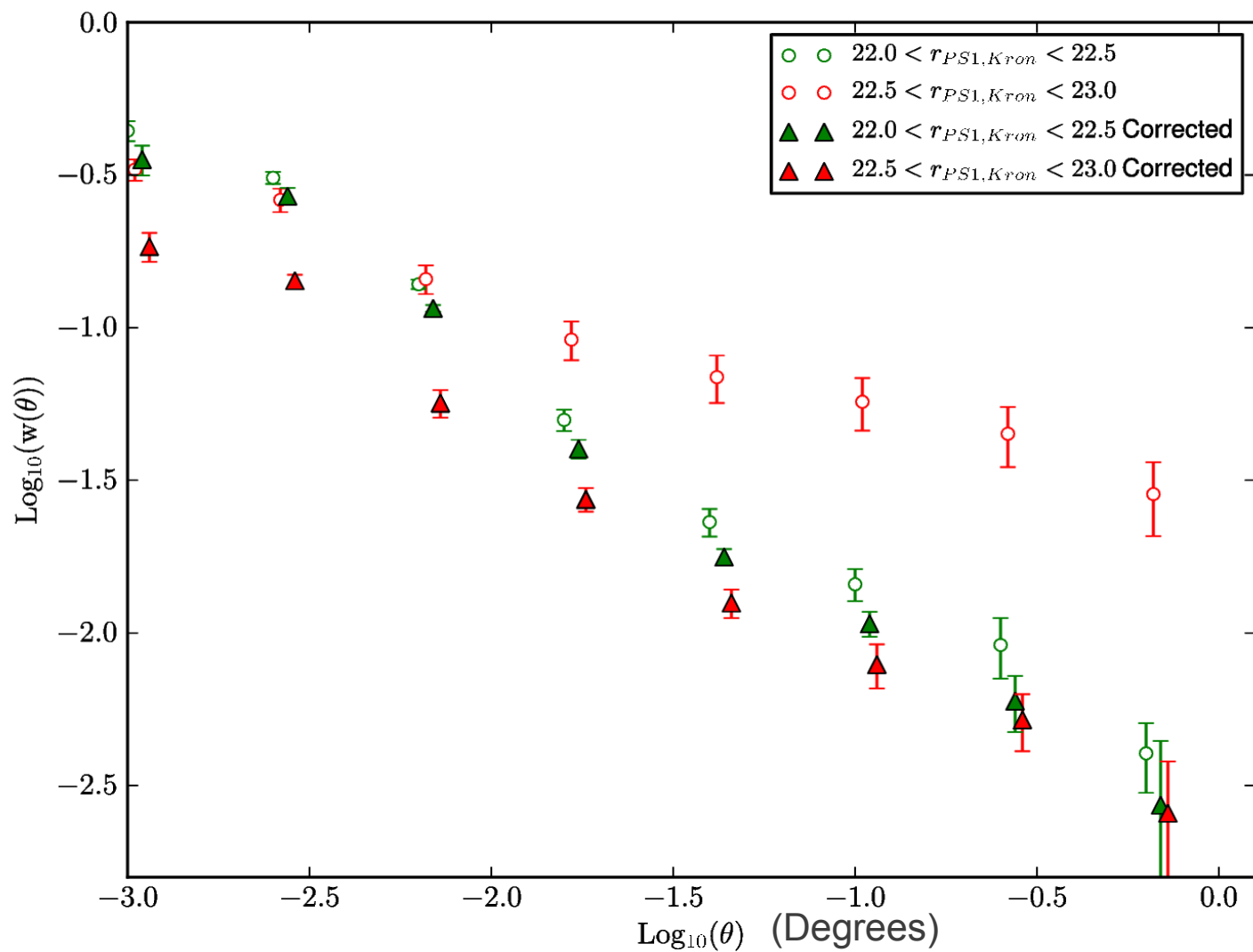
$$SNR = F / \sqrt{\pi * d^2 * variance}$$

- Match an overlap region to Stripe 82 to measure this

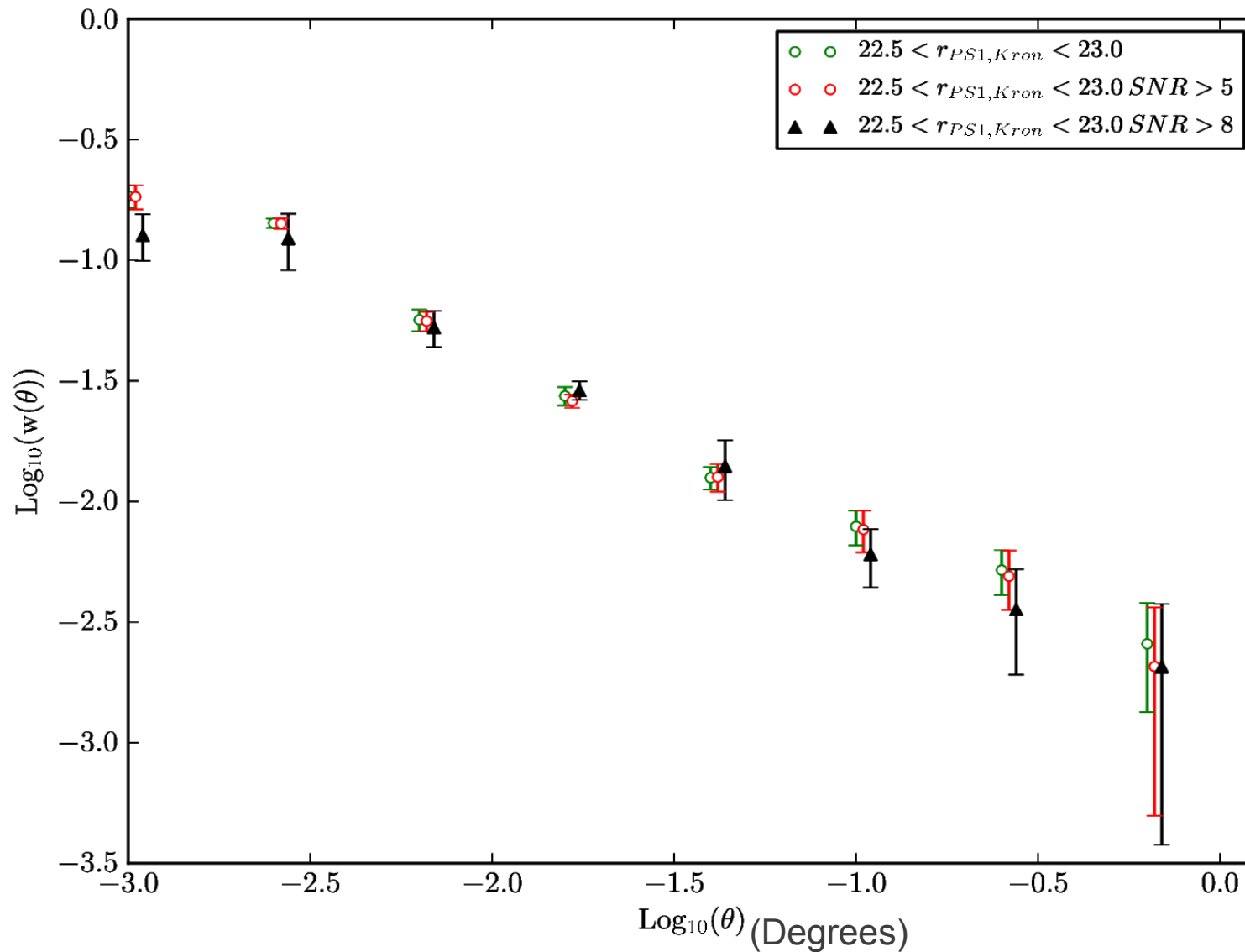
# Fiducial SNR



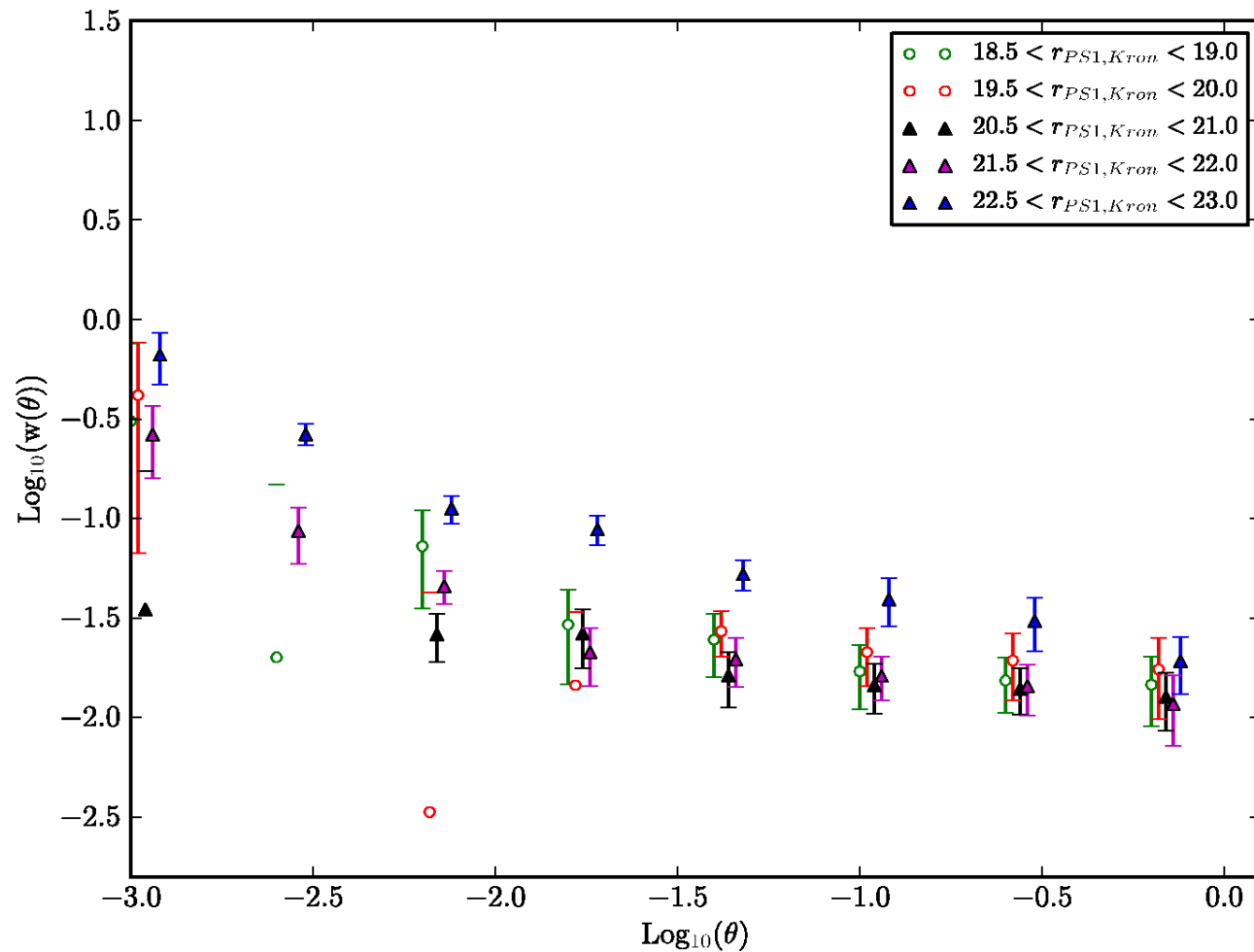
# Correction to clustering



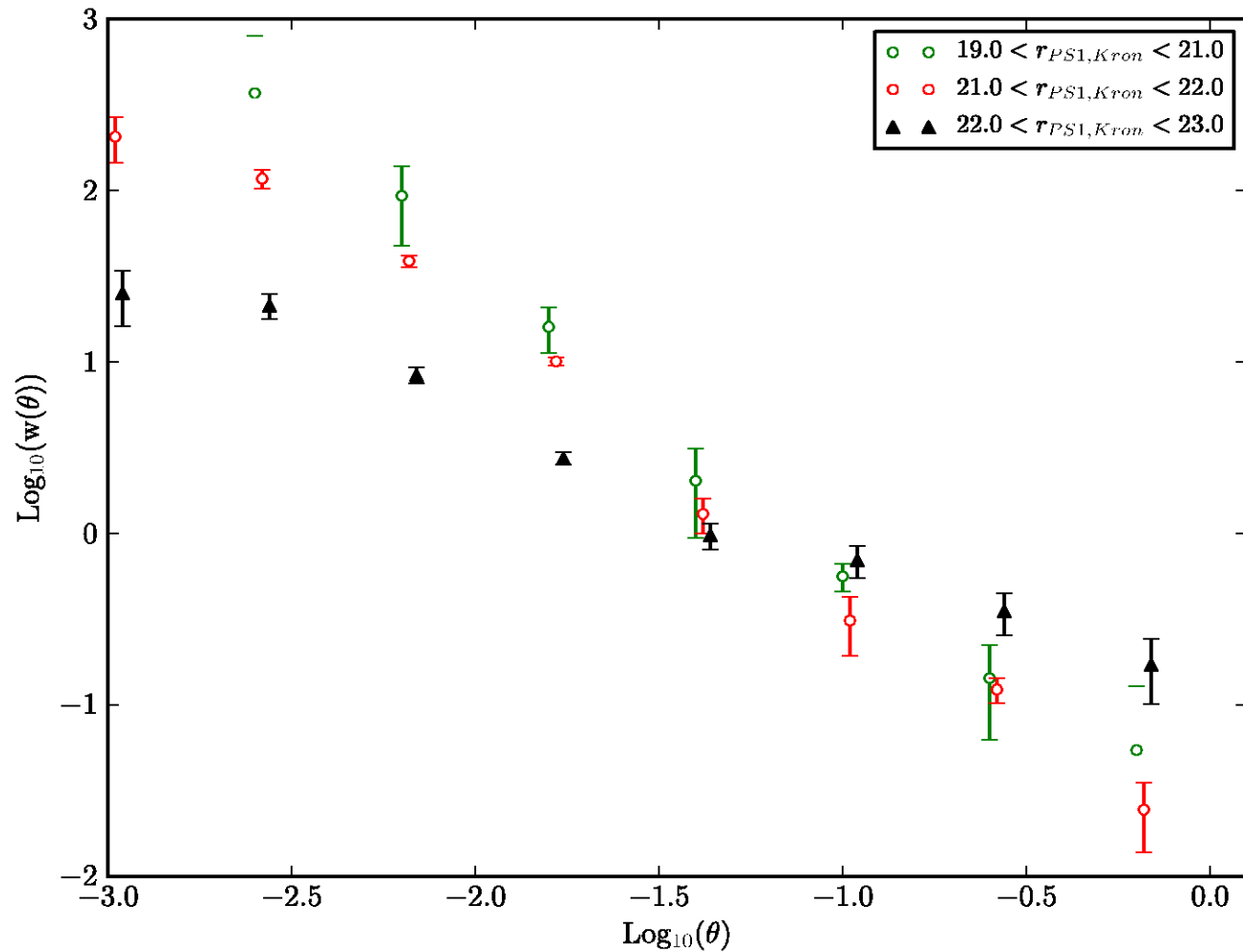
# Tests of method



# Star Clustering

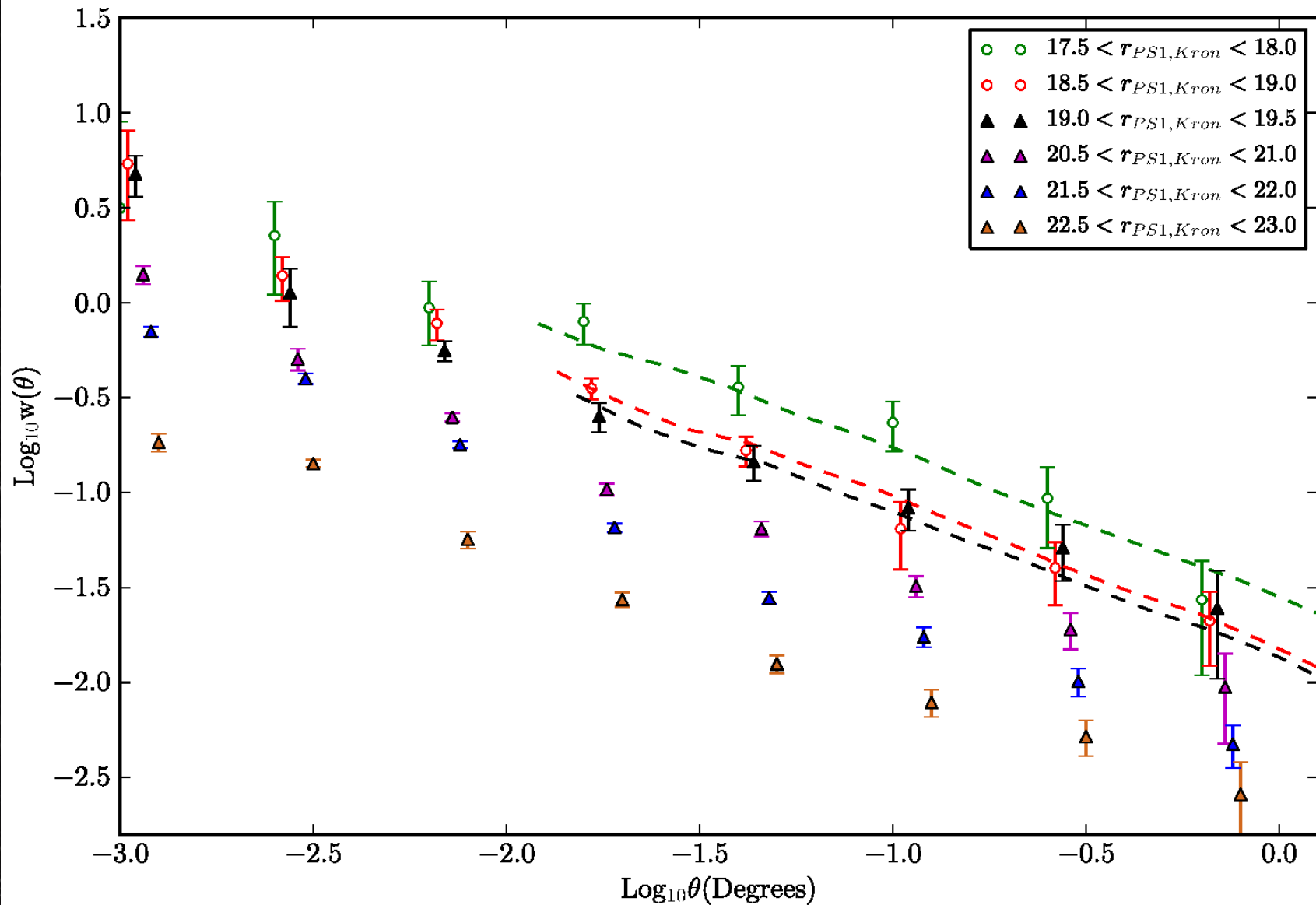


# False Clustering





# Galaxy Clustering



# Conclusions & future

- Presented a method of producing masks and correcting galaxy clustering for variable depth
- Need to extend this to whole  $3\pi$
- Need to decide mask pixel size
- Need to see how well method works with more widely varying PSF FWHM and background
- Can use fakes and comparisons with medium deeps to do this