

7.2 Eigenvectors of L^2

so now we know that $L_z \Phi_m = m\hbar \Phi_m$ where $\Phi_m = (2\pi)^{-1/2} e^{im\phi}$. But we also know that there has to be a common set of eigenfunctions which are BOTH eigenfunctions of L_z AND of L^2 . We will call these $Y_{lm}(\theta, \phi)$. We already know that these have to be eigenfunctions of L_z so

$$L_z Y_{lm}(\theta\phi) = m\hbar Y(\theta\phi)$$

but these must also be eigenfunctions of L^2 so

$$L^2 Y_{lm}(\theta\phi) = l(l+1)\hbar^2 Y_{lm}(\theta\phi)$$

where again we have chosen to scale by \hbar^2 and the reason for calling the eigenvalue $l(l+1)$ will become clear soon!

We can see that $Y_{lm}(\theta\phi)$ must be separable into $\Theta_{lm}(\theta)\Phi_m(\phi)$ where Φ_m is as above and Θ can only be a function of θ and not ϕ as otherwise it would be changed by $L_z = -i\hbar \frac{\partial}{\partial \phi}$ and then this wouldn't be an eigenfunction of both of them.

so solving

$$L^2 Y_{lm}(\theta\phi) = l(l+1)\hbar^2 Y_{lm}(\theta\phi)$$

$$L^2 \Theta(\theta)\Phi_m(\phi) = l(l+1)\hbar^2 \Theta(\theta)\Phi_m(\phi)$$

$$-\hbar^2 \left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right) \Theta(\theta)\Phi_m(\phi) = l(l+1)\hbar^2 \Theta(\theta)\Phi_m(\phi)$$

$$\frac{\Phi}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Theta}{\partial \theta} \right) + \frac{\Theta}{\sin^2 \theta} \frac{\partial^2 \Phi}{\partial \phi^2} = -l(l+1)\Theta(\theta)\Phi_m(\phi)$$

eigenfunctions of L_z had

$$\frac{\partial \Phi_m}{\partial \phi} = im\Phi_m$$

$$\frac{\partial^2 \Phi_m}{\partial \phi^2} = im \frac{\partial \Phi_m}{\partial \phi} = -m^2 \Phi_m$$

substitute in

$$\frac{\Phi}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Theta}{\partial \theta} \right) - \frac{\Theta}{\sin^2 \theta} m^2 \Phi = -l(l+1)\Theta(\theta)\Phi_m(\phi)$$

divide out Φ to get just a function of θ so $\partial/\partial\theta \rightarrow d/d\theta$

$$\frac{1}{\sin\theta} \frac{d}{d\theta} \left(\sin\theta \frac{d\Theta}{d\theta} \right) - \frac{\Theta}{\sin^2\theta} m^2 = -l(l+1)\Theta(\theta)$$

and rearrange

$$\left(\frac{1}{\sin\theta} \frac{d}{d\theta} \left(\sin\theta \frac{d}{d\theta} \right) + l(l+1) - \frac{m^2}{\sin^2\theta} \right) \Theta_{lm} = 0$$

the equation is ugly but well known mathematically. When $m = 0$ the solutions are Legendre polynomials $P_l(\cos\theta)$, where the highest order polynomial term is of order l where $l = 0, 1, 2, \dots$ and is called the orbital angular momentum quantum number some examples are

$$\begin{aligned} P_0(\cos\theta) &= 1 \\ P_1(\cos\theta) &= \cos\theta \\ P_2 &= \frac{1}{2}(3\cos^2\theta - 1) \\ P_3 &= \frac{1}{2}(5\cos^3\theta - 3\cos\theta) \end{aligned}$$

so like the hermite polynomials, the pattern is that even l only has even powers of $\cos\theta$, odd l only has odd powers of $\cos\theta$.

for $m \neq 0$ the solutions are given by the associated Legendre polynomials which are related to the $|m|^{th}$ derivative of P_l . But since P_l is a polynomial of degree l , then its $l+1$ derivative will vanish. so for a fixed value of l , $|m|$ can only take the values $0 \dots l$, so the allowed values of m for a given l are

$$m = -l, -l+1, -l+2 \dots 0, 1, 2 \dots (l-1), l$$

so there are $2l+1$ values of m for every l .

Then we normalise these to get our solutions for $\Theta_{lm}(\theta)$. the normalisation integral is only over θ so $\int \Theta_{lm}^*(\theta) \Theta_{lm}(\theta) \sin\theta d\theta$. then we get

$$\begin{aligned} \Theta_{lm} &= (-1)^m \left(\frac{2l+1}{2} \frac{(l-m)!}{(l+m)!} \right)^{1/2} P_l^m(\cos\theta) \quad m \geq 0 \\ \Theta_{lm} &= (-1)^m \Theta_{l|m|} \quad m < 0 \end{aligned}$$

7.3 Spherical harmonics $Y_{lm}(\theta\phi)$

the eigenvectors common to L^2 and L_z are given by

$$Y_{lm} = \Theta_{lm}\Phi_m = (-1)^m \left(\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!} \right)^{1/2} P_l^m(\cos\theta) e^{im\phi} \quad m \geq 0$$

$$Y_{lm} = (-1)^m Y_{l,-m}^* \quad m < 0$$

with allowed values $m = 0, \pm 1, \pm 2 \dots \pm l$.

we can now see the limit on values which m can take more physically as

$$\langle L^2 \rangle = \langle L_x^2 + L_y^2 + L_z^2 \rangle = \langle L_x^2 \rangle + \langle L_y^2 \rangle + \langle L_z^2 \rangle$$

since these operators are all hermitian then these are all real so

$$\langle L^2 \rangle \geq \langle L_z^2 \rangle$$

$$\begin{aligned} \int \int Y_{lm}^* L^2 Y_{lm} \sin\theta d\theta d\phi &\geq \int \int Y_{lm}^* L_z^2 Y_{lm} \sin\theta d\theta d\phi \\ \int \int Y_{lm}^* l(l+1)\hbar^2 Y_{lm} \sin\theta d\theta d\phi &\geq \int \int Y_{lm}^* L_z (m\hbar Y_{lm}) \sin\theta d\theta d\phi \\ l(l+1)\hbar^2 &\geq \int \int Y_{lm}^* (m^2\hbar^2 Y_{lm}) \sin\theta d\theta d\phi \\ l(l+1) &\geq m^2 \end{aligned}$$

its obviously true for $m = l$, and not true for $m = l+1$ as the rhs is $l^2 + 2l + 1$ which is bigger than the lhs of $l^2 + l$. so this limits the values of $|m| \leq l$

The fact that we have determined L_z means that L_x and L_y cannot be simultaneously determined - if we measure them we will get a value which is quantised at $0, \pm\hbar, \pm 2\hbar$ etc but the actual value is uncertain. However, we can explicitly evaluate their averages, $\langle L_x \rangle$ and $\langle L_y \rangle$. And these both turn out to be zero. so although the particular value of L_x and L_y cannot be predicted, their average value can.

So how do we visualise a system where we have L^2 and L_z with quantised values, but where $\langle L_x \rangle$ and $\langle L_y \rangle = 0$? we can do this with a classical

vector model. The angular momentum vector of magnitude $\sqrt{l(l+1)}\hbar$ precesses around the z axis, so the z component is always fixed at $m\hbar$. Because of the precession, $\langle L_x \rangle$ and $\langle L_y \rangle$ vanish.

so that the angular momentum done. what about the wavefunctions themselves? we can plot these Y_l^m out - A polar plot represents the magnitude (absolute value) of the function as the length of a line centered at the origin, and it represents the values of the angles θ, ϕ by the direction of the line.

but more useful than wavefunctions of course is probability distributions.

The probability of finding the particle within volume $dV = dA = \sin\theta d\theta d\phi$ of position θ, ϕ is $dP = |Y_{lm}|^2 \sin\theta d\theta d\phi$ so if we want the probability density in ϕ then we have to integrate over all theta $dP = D(\phi)d\phi = \int_{\theta=0}^{\pi} |Y_{lm}|^2 \sin\theta d\theta d\phi$ conversely, if we wanted the probability density in θ we'd do $dP = D(\theta)d\theta = \int_0^{2\pi} |Y_{lm}|^2 d\phi \sin\theta d\theta$ similarly, if we want the probability per unit area on a sphere, then its $dP dA = |Y_{lm}|^2 dA$ so

$$D(A) = Y_{lm}^* Y_{lm} = \Theta_{lm}^* \Phi_m^* \Theta_{lm} \Phi_m = (2\pi)^{-1} \Theta_{lm}^* \Theta_{lm}$$

The ϕ dependence drops out, so the probability of finding the particle is independent of ϕ so we can plot these more easily. This gives a polar diagram, showing the dependence of the probability on θ . A polar plot represents the magnitude (absolute value) of the function as the length of a line centered at the origin, and it represents the values of the angle θ by the direction of the line.