

Figure 3: The probability distribution

as potential clusters – see Figure 3. The solution is to use method 1 for cluster identification.

function (PDF) for the density in the environments detected using the two methods. Continuous lines give the density MMF results while the dashed lines give the second method results. Environments correspond to a wide range of densities, so a simple density threshold does not suffice in identifying the Cosmic Web environments.

	Volume fraction (%)		Mass fraction (%)	
	Method 1	Method 2	Method 1	Method 2
clusters	0.02	0.03	7	5
filaments	4	3	42	35
walls	6	4	9	12
field	90	93	42	48

Table 1: The volume and mass fraction inthe environments detected using the twomethods.

Method 2 also better captures the expected halo population in walls (the density MMF wall population has an unexpected deficiency of high mass halos compared to the field).



Figure 4: The halo mass function (for AHF halos – Knollmann & Knebe 2009) for the halos that reside in the different Cosmic Web environments. density in the environments detected using the two methods. *Left-panel:* First method results. *Right-panel:* Second method results.



Figure 2: The Cosmic Web environments obtained using the **density logarithm MMF** method (100 x 100 x 20 (Mpc/h)³ slice from an N-body dark matter only simulation):

Upper-left: Logarithmic rendering of the density field in the slice. Upper-right: MMF clusters (blue) and filaments (red transparent). Lower-left: MMF filaments (red) and walls (green transparent). Lower-right: MMF walls (green).

- 1. Aragon-Calvo, M.A., Jones, B.J.T., van de Weygaert, R., van der Hulst, J.M., TheMultiscale Morphology Filter", 2007, Apj, 474, p. 315
- Knollmann, S.R., Knebe, A., "AHF: Amiga's Halo Finder", 2009, AJS, 182, pp. 608
- 3. Cautun, M., van de Weygaert, R., Jones, B.J.T., "Cosmic Web environment detection", in prep.