

Gravitational growth: lensing and redshift space distortions

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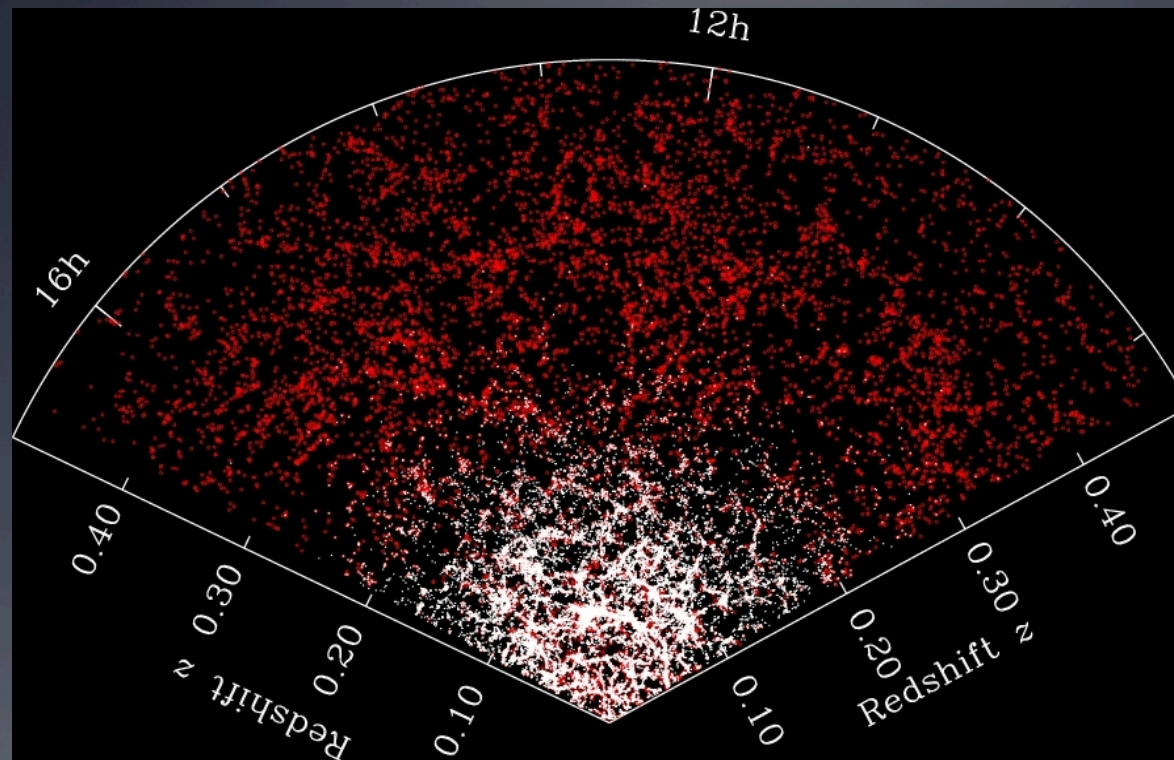
Durham, July 25, 2013

Overview

- To measure growth of structure need 3-d information: galaxies
- Galaxies are not dark matter: biasing: the large scale structure view
- Easy way: galaxy clustering combined with galaxy-shear lensing: current constraints from SDSS some of the best in weak lensing
- Hard way: galaxy clustering in redshift space: redshift space distortions. Has the potential but is subject to a lot of complications
- Combining the two can probe modifications of gravity

Collaborators: T. Baldauf, V. Desjacques, R. Mandelbaum, P. McDonald, T. Okumura, A. Slosar, Z. Vlah, J. Yoo

Galaxy clustering in redshift space

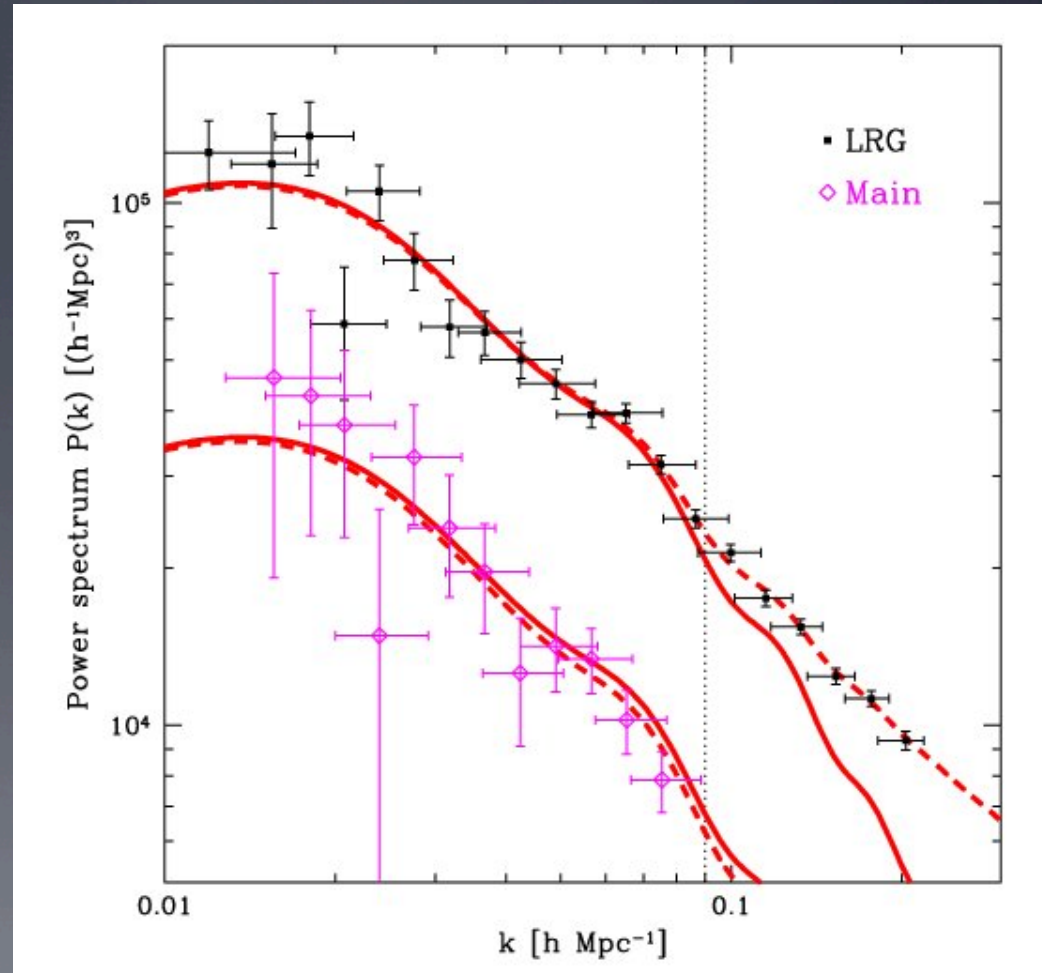


SDSS

- 1) Measures 3-d distribution, has many more modes than projected quantities like shear from weak lensing
- 2) Easy to measure: effects of order unity, not 1%

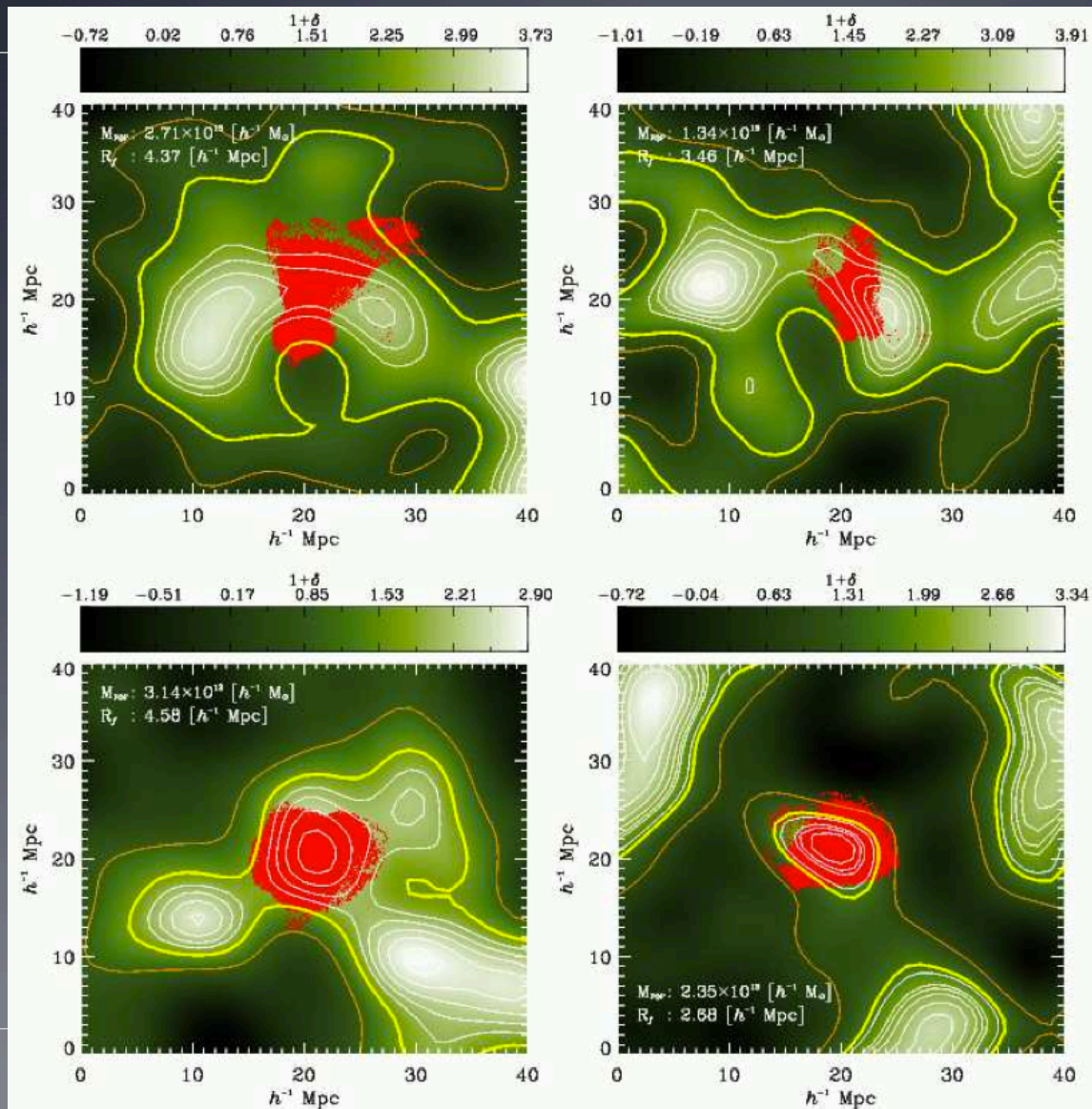
Power Spectrum

- Galaxy clustering traces dark matter clustering: 3-d analysis contains a lot of statistical information
- Amplitude depends on galaxy type: galaxy bias b
$$P_{gg}(k) = b^2(k) P_{mm}(k)$$
- To determine bias we need additional (external) information
- Galaxy bias can be scale dependent: $b(k)$
- Once we know bias we know how dark matter clustering grows in time



Tegmark et al. (2006)

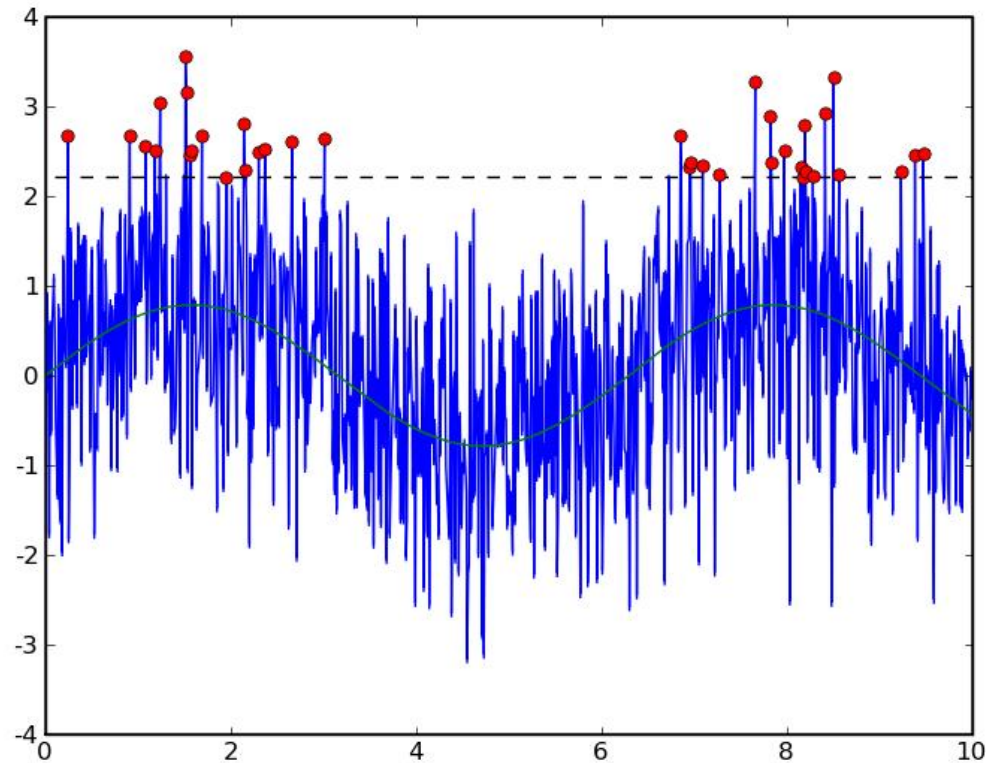
Most halos form at initial density peaks



Complication I: why are galaxies biased?

Galaxies form at high density peaks of initial density:

rare peaks are more strongly clustered



The enhancement depends on the halo mass function slope

Bias model I: local bias

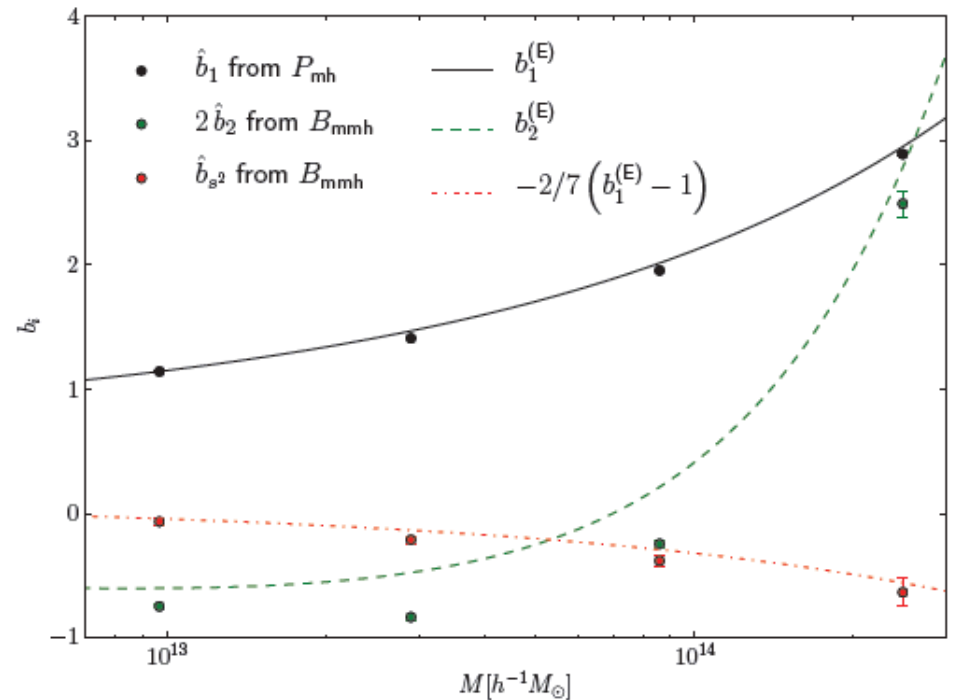
Local bias model: $\delta_h = b_1 \delta_m + b_2 \delta_m^2 + \dots$

Peak-background split model:
 b_1 is determined by 1st derivative
of halo mass function,
 b_2 by 2nd derivative...

$$b_{10}^L = \frac{1}{\bar{n}} \frac{\partial n}{\partial \delta_1} = -\frac{1}{\bar{n}} \frac{2\nu}{\delta_c} \frac{\partial n}{\partial \nu}$$

$$b_{01}^L = \frac{1}{\bar{n}} \frac{\partial n}{\partial \varphi_1} = -\frac{4f_{\text{NL}}\nu}{\bar{n}} \frac{\partial n}{\partial \nu} = 2f_{\text{NL}}\delta_c b_{10}^L$$

$$b_{20}^L = \frac{1}{\bar{n}} \frac{\partial^2 n}{\partial \delta_1^2} = \frac{4\nu^2}{\bar{n}} \frac{\partial^2 n}{\partial \nu^2} + \frac{2\nu}{\bar{n}} \frac{\partial n}{\partial \nu}$$



Bias model II: non-local bias

Local bias model: $\delta_h = b_1 \delta_m + b_2 \delta_m^2 + \dots$: Eulerian or Lagrangian?

Gravity develops nonlocal terms

$${}^{(2)}\delta(\mathbf{x}, \eta) = \frac{17}{21} {}^{(1)}\delta^2(\mathbf{x}, \eta) - \Psi(\mathbf{x}, \eta) \cdot \nabla \delta(\mathbf{x}, \eta) + \frac{2}{7} s^2(\mathbf{x}, \eta).$$

Tidal tensor

$$s_{ij}(\mathbf{x}, \eta) = \partial_i \partial_j \Phi(\mathbf{x}, \eta) - \frac{1}{3} \delta_{ij}^{(K)} \delta(\mathbf{x}, \eta).$$

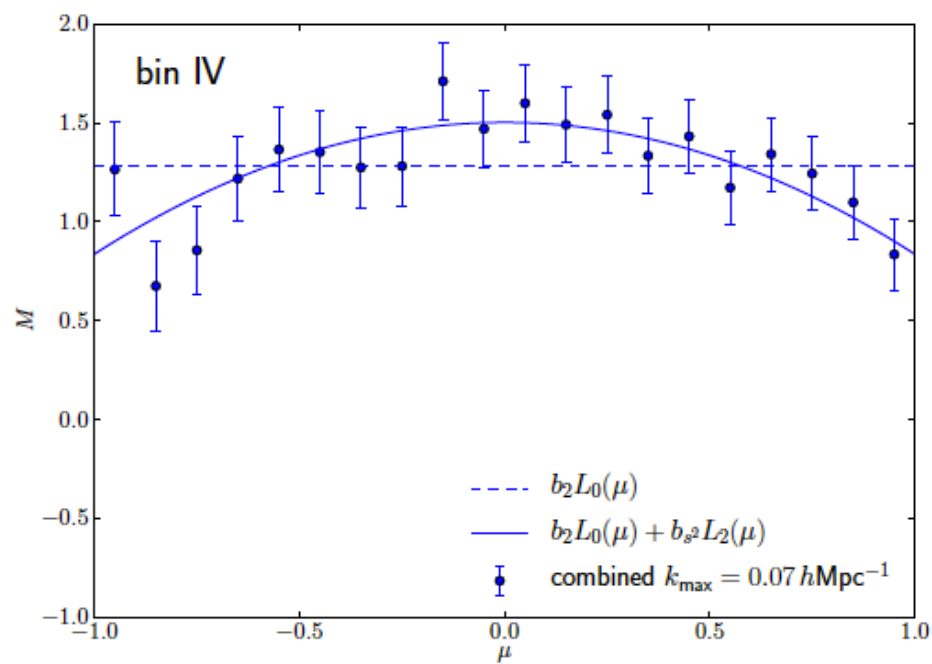
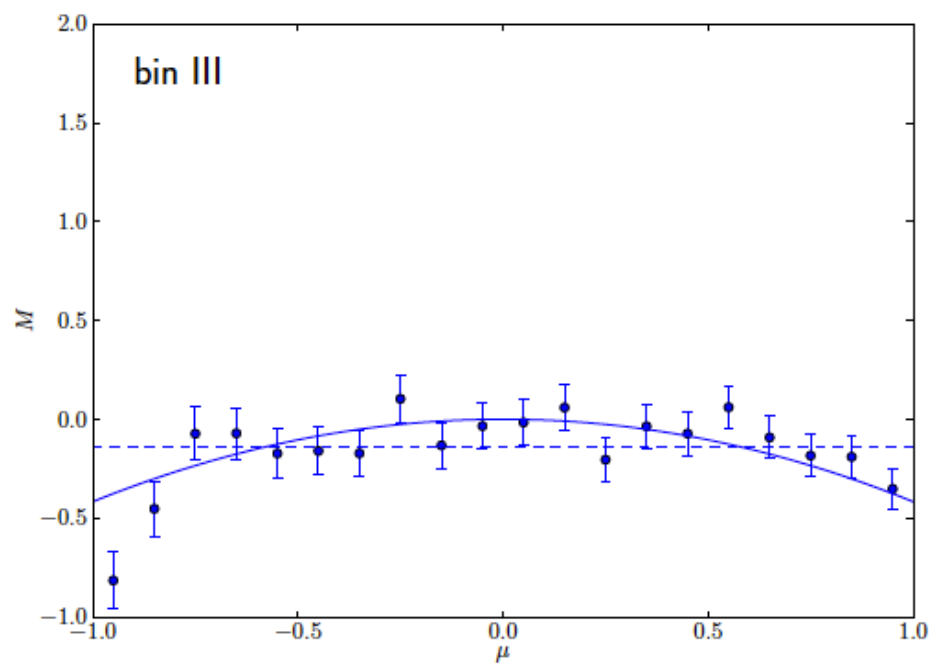
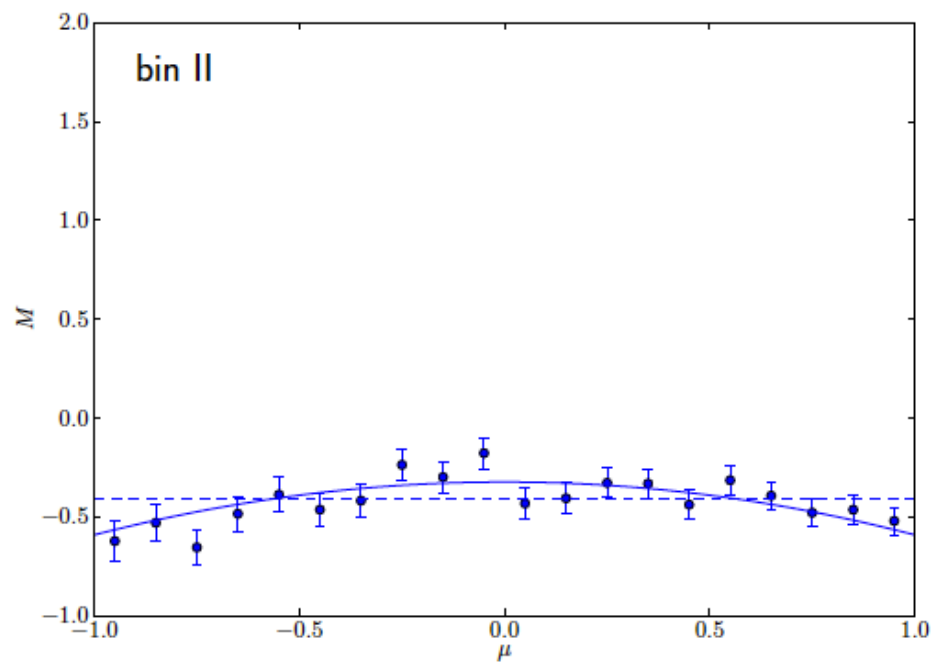
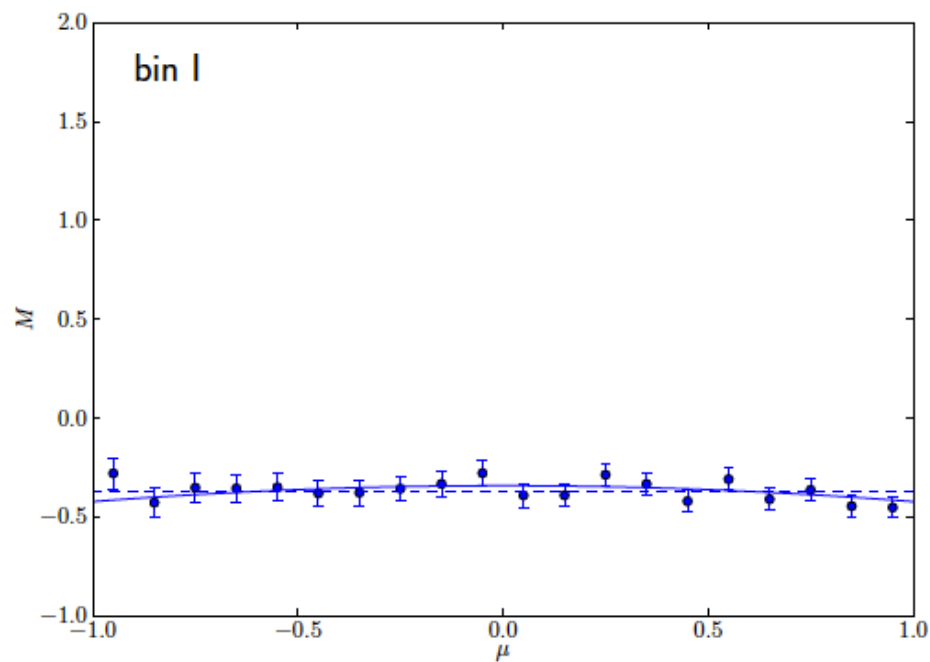
Baldauf et al, Kwan et al 2012

$$\delta_h(\mathbf{x}, \eta) = b_1 \delta(\mathbf{x}, \eta) + b_2 [\delta^2(\mathbf{x}, \eta) - \langle \delta^2(\mathbf{x}, \eta) \rangle] + b_{s^2} [s^2(\mathbf{x}, \eta) - \langle s^2(\mathbf{x}, \eta) \rangle]$$

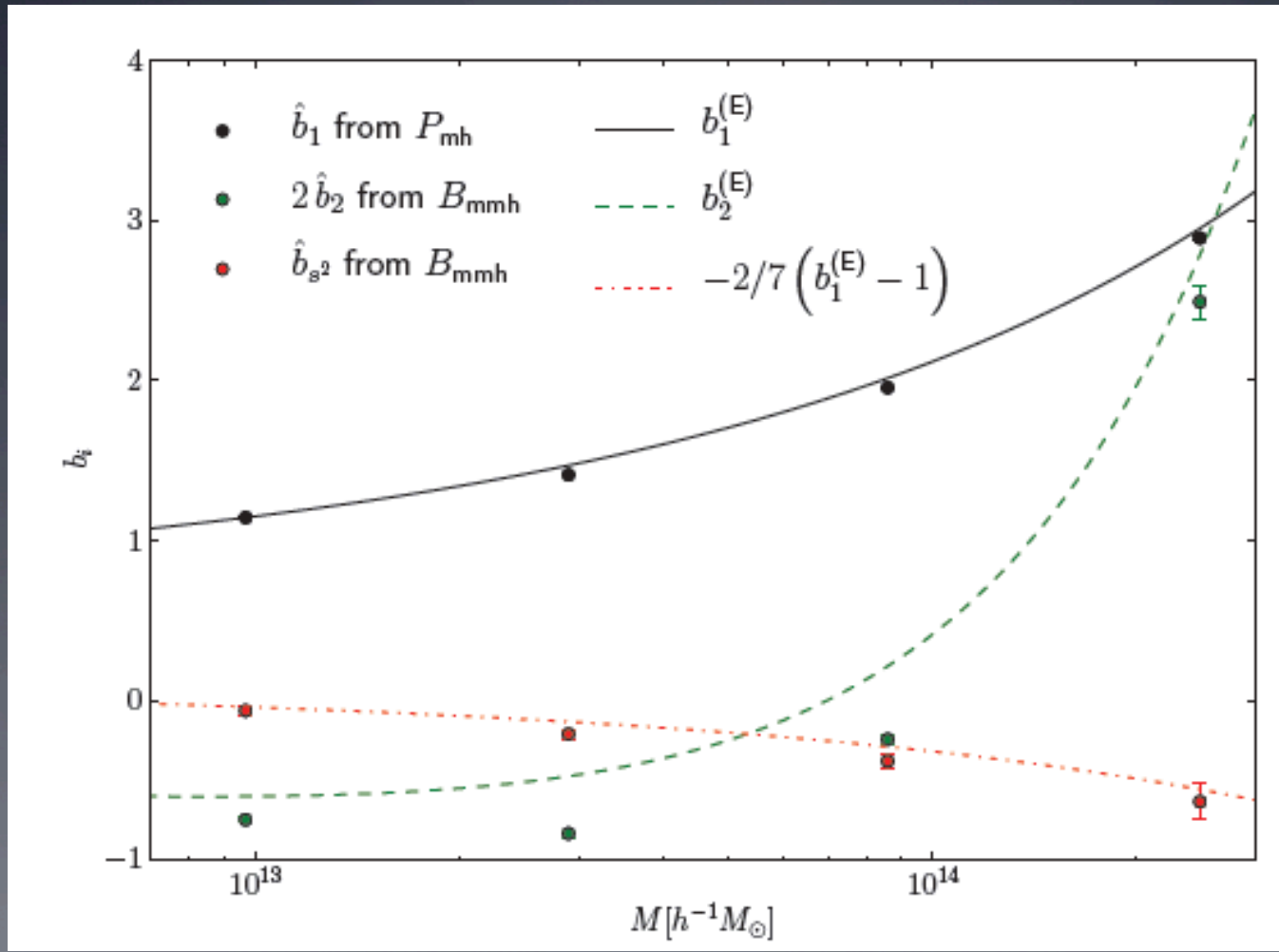
Local Lagrangian bias model predicts $b_{s^2} = -2(b_1 - 1)/7$

We can look for it in bispectrum B_{mmh}

$$B_{mmh}^{(\text{unsym})}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3) - b_1 B_{mmm}(\mathbf{k}_1, \mathbf{k}_2, \mathbf{k}_3) = 2P(k_1)P(k_2) \left[b_2 + b_{s^2} \left(\mu^2 - \frac{1}{3} \right) \right].$$



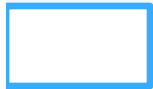
Bispectrum fits to simulations vs peak-background split predictions



Bottom line: non-local bias exists, not possible to ignore it

3rd order non-local bias

Let's write all possible terms allowed by symmetry at 3rd order (McDonald and Roy 2010)



2nd-order non-local bias
(tidal bias)

$$B^{hmm} \sim \langle \delta_h^{(2)} \delta_m^{(1)} \delta_m^{(1)} \rangle$$



3rd-order non-local bias

~~$$T^{hmmmm} \sim \langle \delta_h^{(3)} \delta_m^{(1)} \delta_m^{(1)} \delta_m^{(1)} \rangle$$~~

$$P^{hm} \sim \langle \delta_h^{(1)} \delta_m^{(1)} \rangle + \langle \delta_h^{(1)} \delta_m^{(3)} \rangle + \langle \delta_h^{(2)} \delta_m^{(2)} \rangle + \langle \delta_h^{(3)} \delta_m^{(1)} \rangle$$

linear bias x P^{NL}_m

Combining P(k) with B(k) → 3rd-order nonlocal bias!

local bias

$$\delta_h(\mathbf{x}) = c_\delta \delta_m(\mathbf{x}) + \frac{1}{2} c_{\delta^2} \delta_m(\mathbf{x})^2 + \frac{1}{3!} c_{\delta^3} \delta_m(\mathbf{x})^3 + c_\epsilon \epsilon + \dots,$$

non-local bias **linear**: can be measured via $P^{hm}(k)$ at large scales

$$+ \frac{1}{2} c_{s^2} s(\mathbf{x})^2$$

2nd-order: measured via $B^{hmm}(k)$ at large scales

$$+ \frac{1}{2} c_{\delta s^2} \delta_m(\mathbf{x}) s(\mathbf{x})^2 + c_\psi \psi(\mathbf{x}) + c_{st} s(\mathbf{x}) t(\mathbf{x}) + \frac{1}{3!} c_{s^3} s(\mathbf{x})^3$$

3rd-order

where

$$s_{ij}(\mathbf{x}) \equiv \partial_i \partial_j \phi(\mathbf{x}) - \frac{1}{3} \delta_{ij}^K \delta_m(\mathbf{x}) = \left[\partial_i \partial_j \partial^{-2} - \frac{1}{3} \delta_{ij}^K \right] \delta_m(\mathbf{x}), \quad \text{tidal field}$$

$$t_{ij}(\mathbf{x}) \equiv \partial_i v_j - \frac{1}{3} \delta_{ij}^K \theta_m(\mathbf{x}) - s_{ij}(\mathbf{x}) = \left[\partial_i \partial_j \partial^{-2} - \frac{1}{3} \delta_{ij}^K \right] [\theta(\mathbf{x}) - \delta_m(\mathbf{x})],$$

$$\psi(\mathbf{x}) \equiv [\theta(\mathbf{x}) - \delta_m(\mathbf{x})] - \frac{2}{7} s(\mathbf{x})^2 + \frac{4}{21} \delta_m(\mathbf{x})^2.$$

(halo density)-(matter density) McDonald & Roy (2010)

$$P_{00}^{hm}(k) = \left(c_\delta + \frac{34}{21} c_{\delta^2} \sigma^2 + \frac{1}{2} c_{\delta^3} \sigma^2 + \frac{1}{3} c_{\delta s^2} \sigma^2 + \frac{1}{2} c_{\delta \epsilon^2} \sigma_\epsilon^2 + \frac{68}{63} c_{s^2} \sigma^2 - \frac{16}{63} c_{st} \sigma^2 \right) P_{\delta\delta}^{NL}(k)$$

origin: (1)x(1) or (1)x(3) → linear bias

$$+ c_{\delta^2} \int \frac{d^3 q}{(2\pi)^3} P(q) P(|\mathbf{k} - \mathbf{q}|) F_S^{(2)}(q, \mathbf{k} - \mathbf{q})$$

$$+ c_{s^2} \int \frac{d^3 q}{(2\pi)^3} P(q) P(|\mathbf{k} - \mathbf{q}|) F_S^{(2)}(q, \mathbf{k} - \mathbf{q}) S^{(2)}(q, \mathbf{k} - \mathbf{q})$$

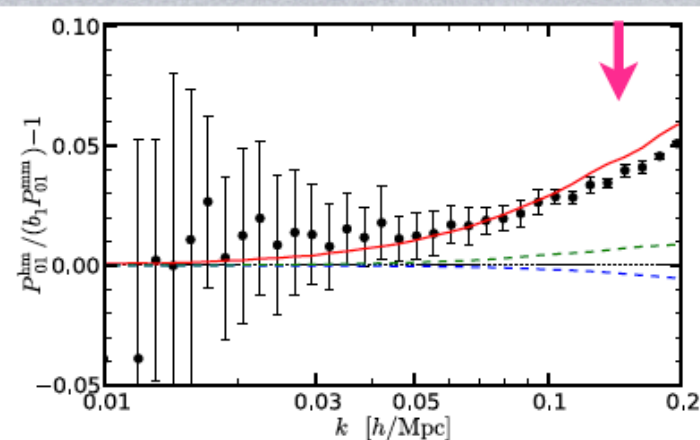
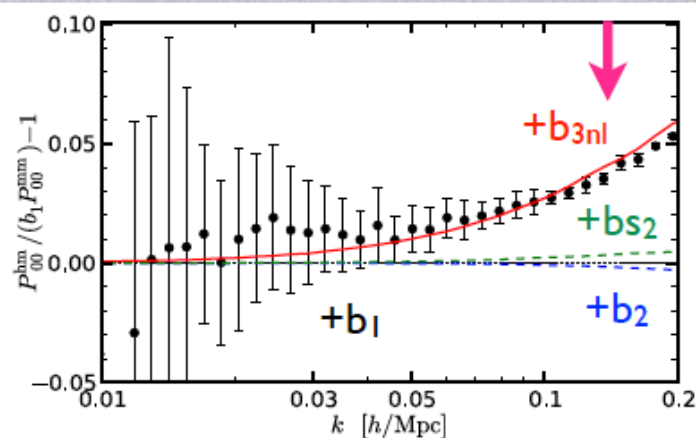
$$+ \left(-\frac{16}{21} c_{s^2} + \frac{32}{105} c_{st} + \frac{512}{2205} c_\psi \right) \sigma_3^2(k) P(k)$$

$$= b_1 P_{\delta\delta}^{NL}(k) + b_2 P_{b2,\delta}(k) + b_{s^2} P_{bs2,\delta}(k) + b_{3nl} \sigma_3^2(k) P(k),$$

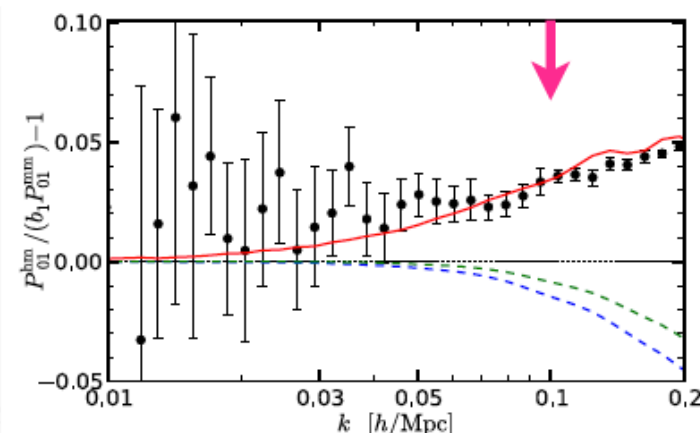
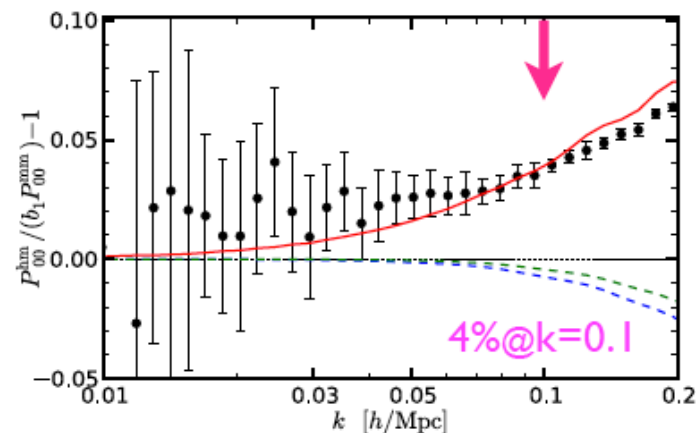
(halo density)-(matter density)

(halo density)-(matter momentum)

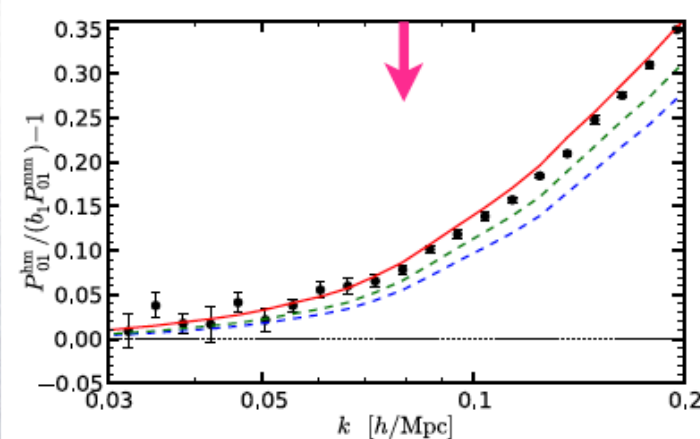
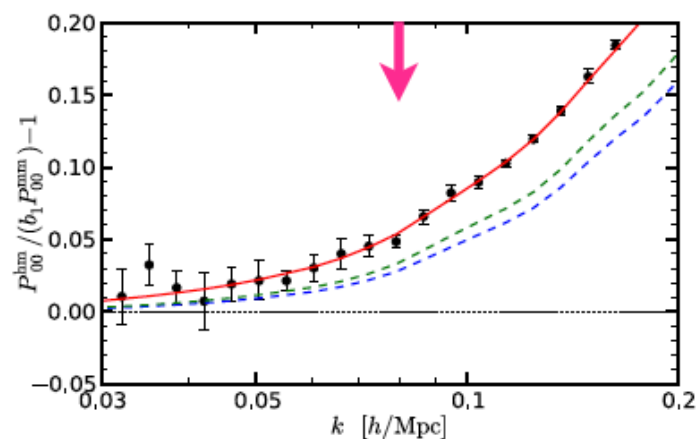
z=1
lightest



z=0.5
CMASS



z=0
massive bin

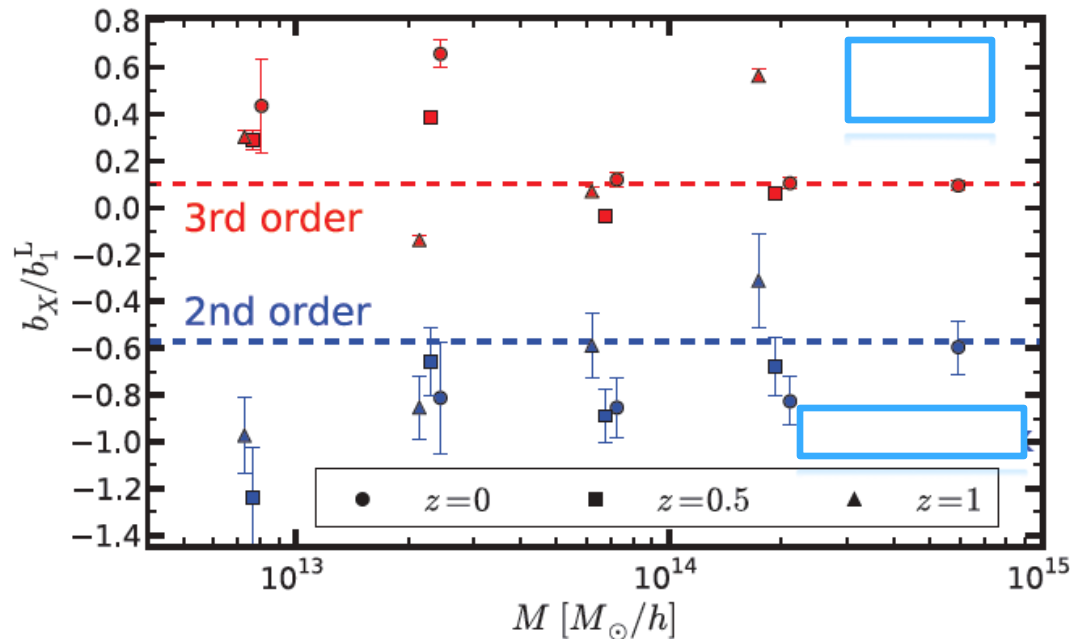


Prediction from local bias in Lagrangian space

The simple co-evolution picture predicts non-local bias as

2nd order $b_{s^2} = -\frac{4}{7}b_1^L = -\frac{4}{7}(b_1^E - 1)$

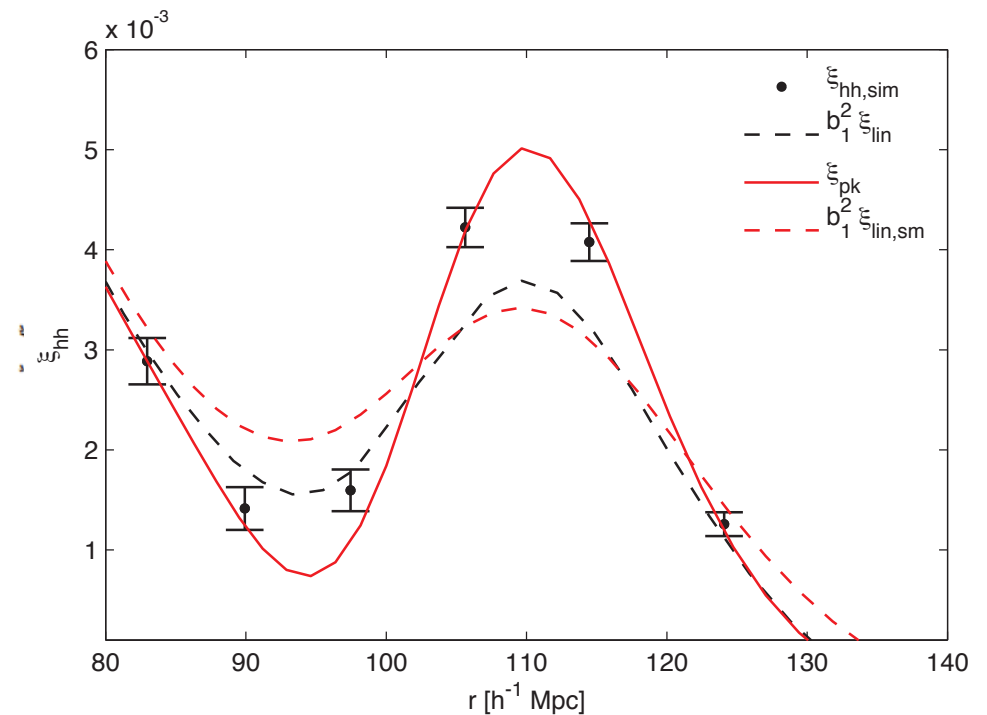
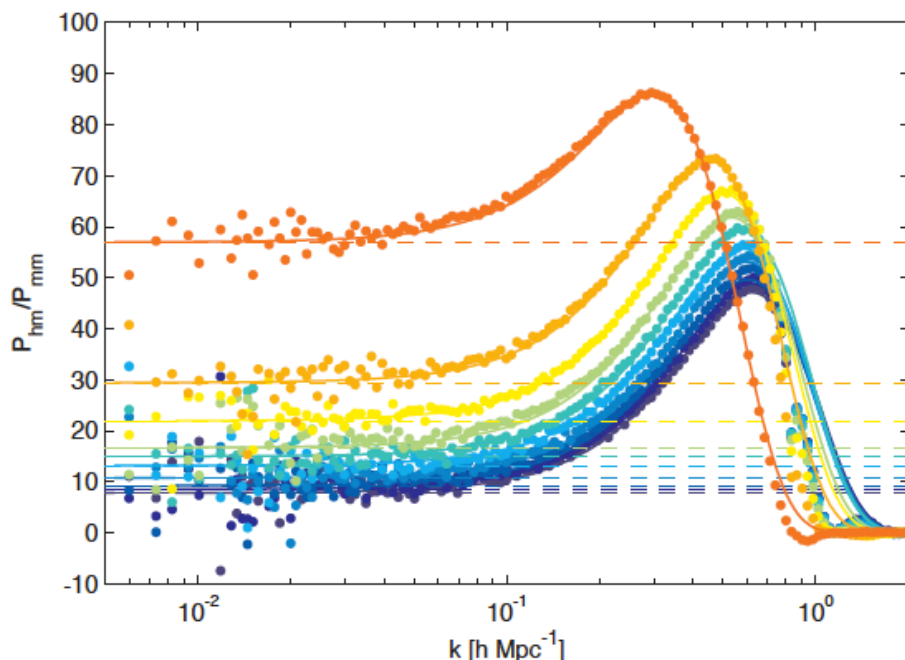
3rd order $b_{3nl} = \frac{32}{315}b_1^L = \frac{32}{315}(b_1^E - 1)$



Bias model III: linear peak biasing for proto-halos

- Peak constraints depend also on 2nd derivatives of density field, in low k limit one can expand to find (Desjacques 2008)

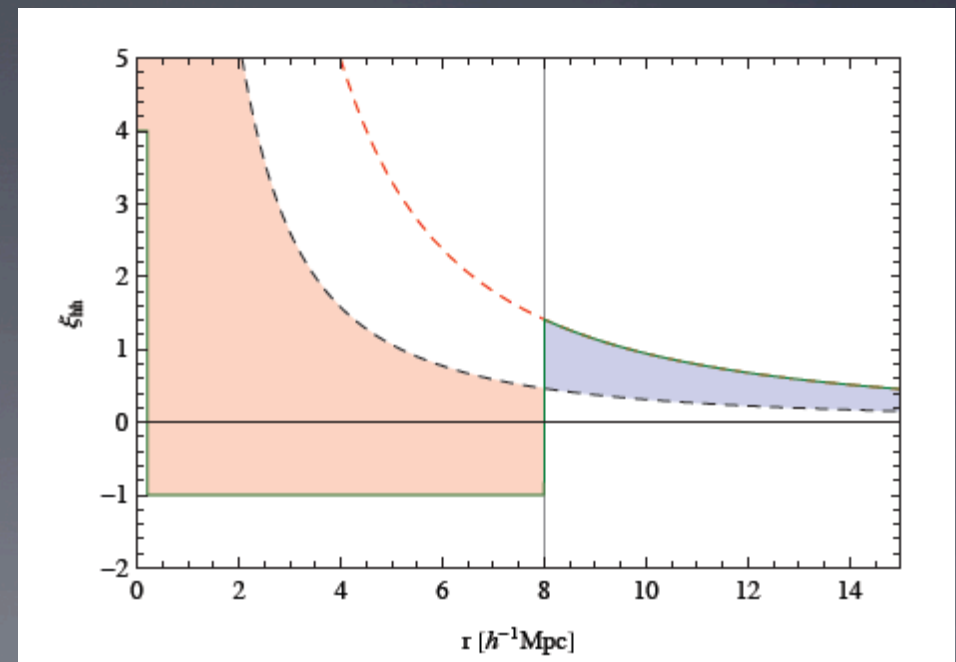
$$P_{\text{hm}}(k) = (b_\nu + b_\zeta k^2) W_{G,R_{\text{pk}}}(k) P(k) \quad | \quad P_{\text{hh}}(k) \approx (b_\nu + b_\zeta k^2)^2 W_{G,R_{\text{pk}}}^2(k) P(k)$$



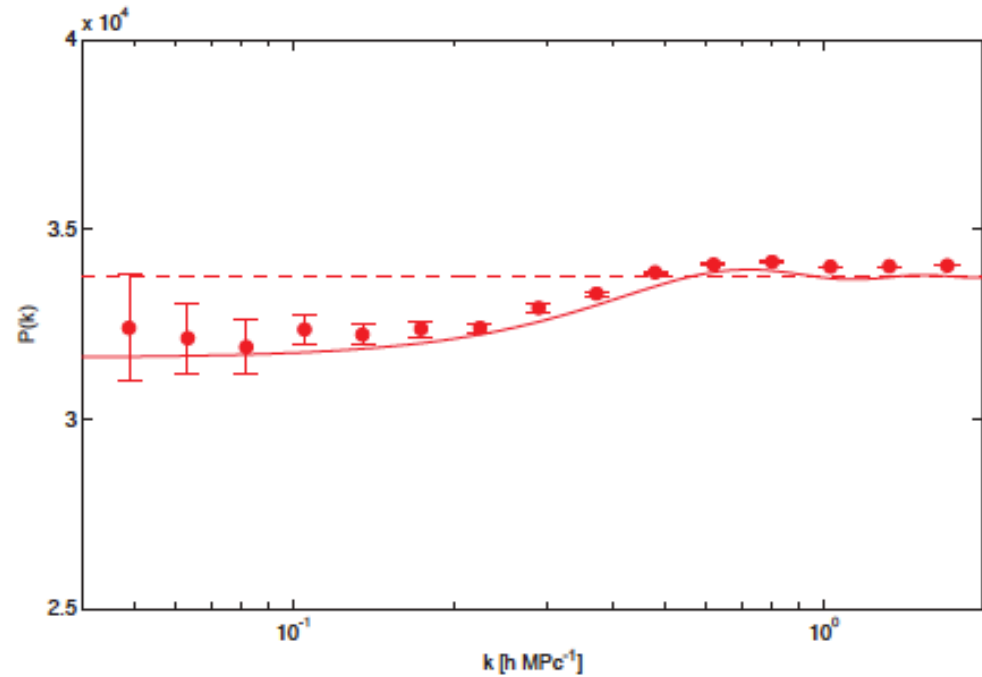
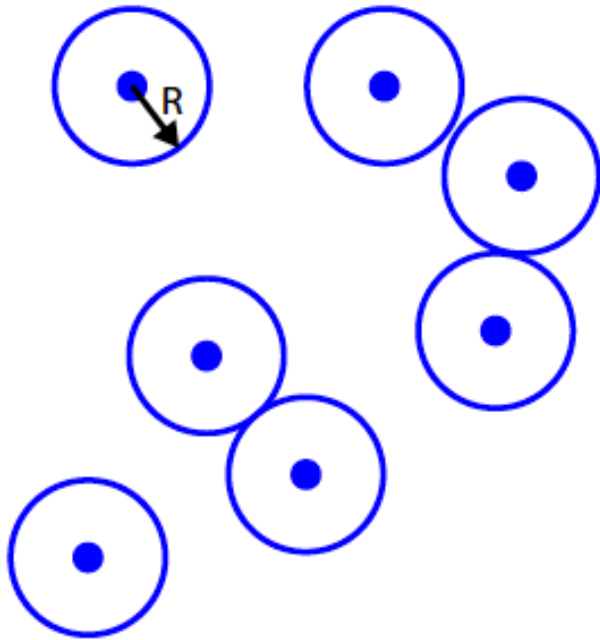
k^2 effects likely survive to $z=0$, but are pushed to smaller scales

Bias model IV: stochasticity from exclusion and nonlinearity

- We managed to explain P_{hm} , what about P_{hh} ?
- Define stochasticity as $\sigma^2 = \langle (\delta_h - b\delta_m)^2 \rangle = P_{hh} - 2bP_{hm} + b^2P_{mm}$
- If we can model $\sigma^2(k)$ we can model P_{hh}
- Standard model:
Poisson shot noise $\sigma^2 = 1/n$
- 2 corrections: exclusion, nonlinear clustering



Random Sample with Exclusion



Perturbation Theory + Exclusion

$$\sigma_{ij}(k) = \frac{1}{\bar{n}} - [P_{\text{disc}} * W](k) + \frac{1}{2} b_{2,i} b_{2,j} \int \frac{d^3 q}{(2\pi)^3} P(q) P(\mathbf{k} - \mathbf{q})$$

Dependence on halo mass

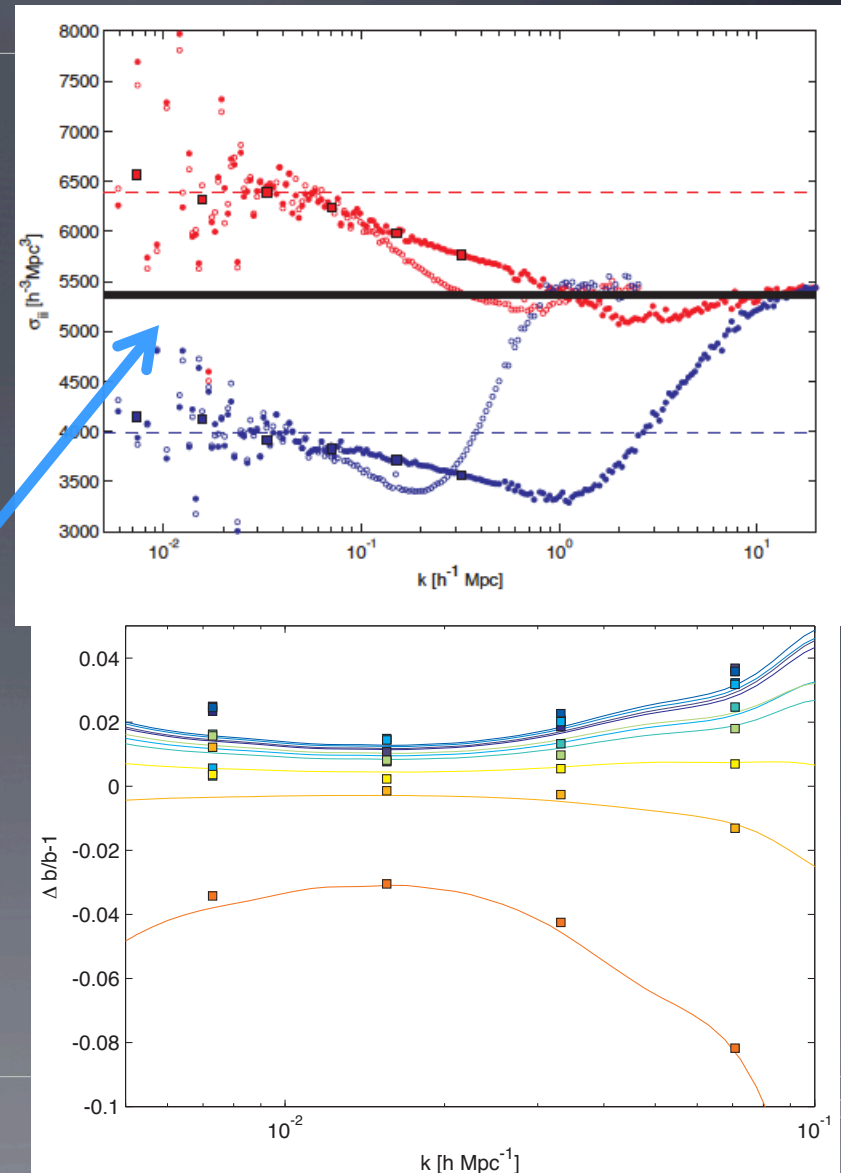
Same value of $\sigma^2(k=0)$
between $z=z_{\text{in}}$ and $z=0$: gravity
cannot modify it

Positive (nonlinear effects
dominate) for low mass, negative
(exclusion dominates) for high
mass

At high k 0 correction to $1/n$

Transition scale shrinks at $z=0$
relative to $z=z_{\text{in}}$

Effects of order a few %



The large scale structure view of biasing

Q: Can we predict non-linear biasing or do we need 5+ new parameters?

A: Sort of: most of the effects are related to the halo mass. It may be possible to reduce all these effects to a single parameter, but we have not yet demonstrated that

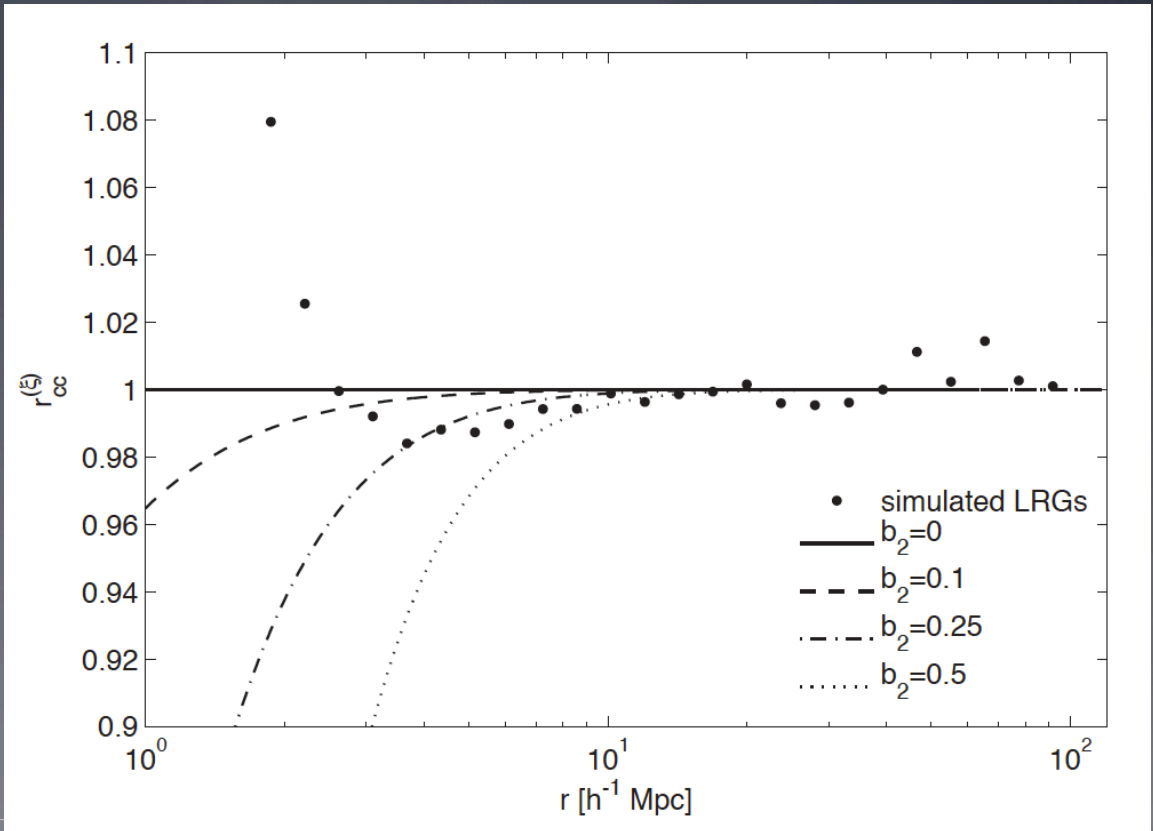
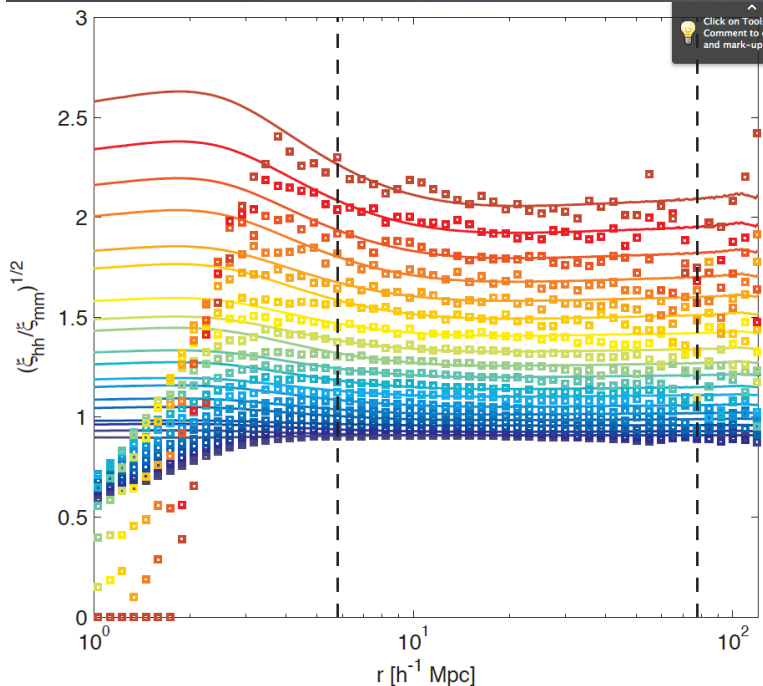
Q: What is the simplest way to reduce the nonlinear biasing?

A: Most of the biasing effects show up in auto and cross-correlation statistics, they cancel in cross-correlation coefficient

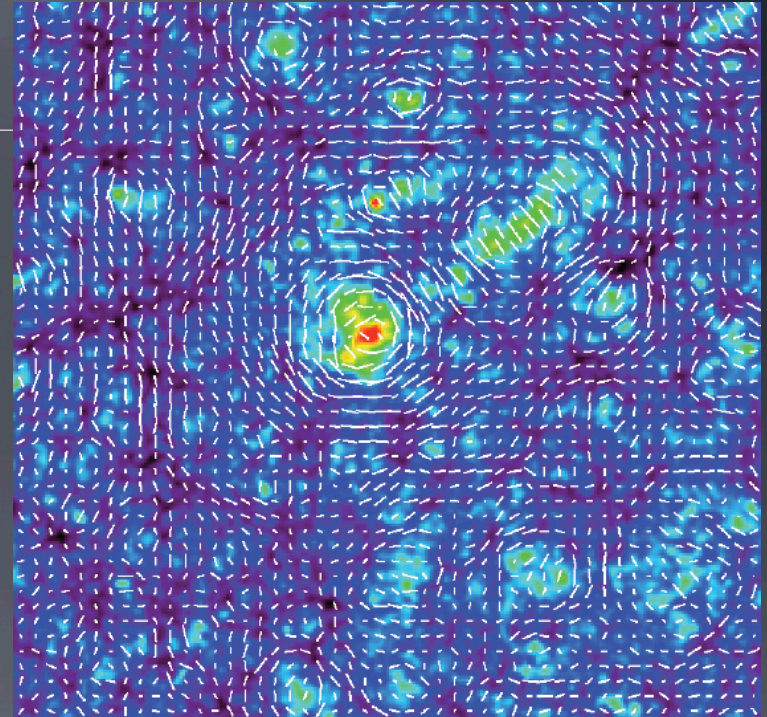
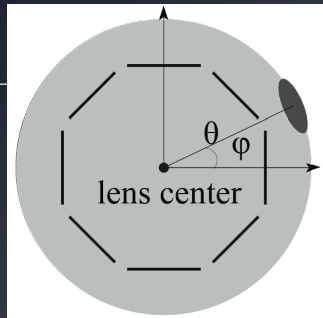
Halo dark matter cross-correlation coefficient: LRG simulations

as long as galaxies are inside halos we get nearly the same correlation coefficient independent of how galaxies occupy halos

$$r = \frac{\xi_{hm}}{\sqrt{\xi_{hh}\xi_{mm}}}$$



Galaxy-dark matter correlations: galaxy-shear lensing



$$R = r_L \Theta$$

$$\gamma_T = \frac{\Delta\Sigma(R)}{\Sigma_{crit}}$$

$$\Delta\Sigma(R) = \bar{\Sigma}(R) - \Sigma(R)$$

$$\Sigma(R) = \int \rho(\sqrt{R^2 + \chi^2}) d\chi$$

$$\Sigma_{crit} = \frac{c^2}{4\pi G} \frac{D_S}{D_L D_{LS} (1 + z_L)^2}$$

Statistics for halo-shear lensing

- Problem: cross-correlation coefficient does not follow RPT on small scales (halo exclusion, nonlinear effects, satellites)
- Shear is sensitive to small scale information

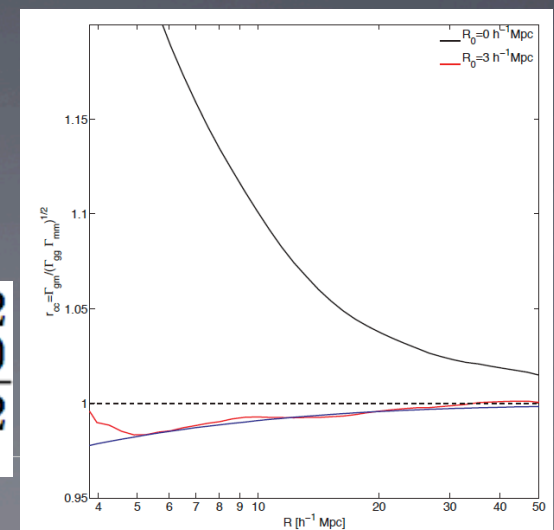
$$\Sigma(R) = \int g(\chi) \xi(\sqrt{\chi^2 + R^2}) d\chi$$

$$\Delta\Sigma = \bar{\Sigma}(R) - \Sigma(R) = \int_0^R R' dR' \Sigma(R') - \Sigma(R)$$

We introduced (Baldauf et al 2009) new statistic that cancels small scale information

$$\Upsilon(R) = \Delta\bar{\Sigma}(R) - \Delta\Sigma(R_0) \frac{R_0^2}{R^2} =$$

$$= \frac{2}{R^2} \int_{R_0}^R R' dR' \Sigma(R') - \Sigma(R) + \Sigma(R_0) \frac{R_0^2}{R^2}$$

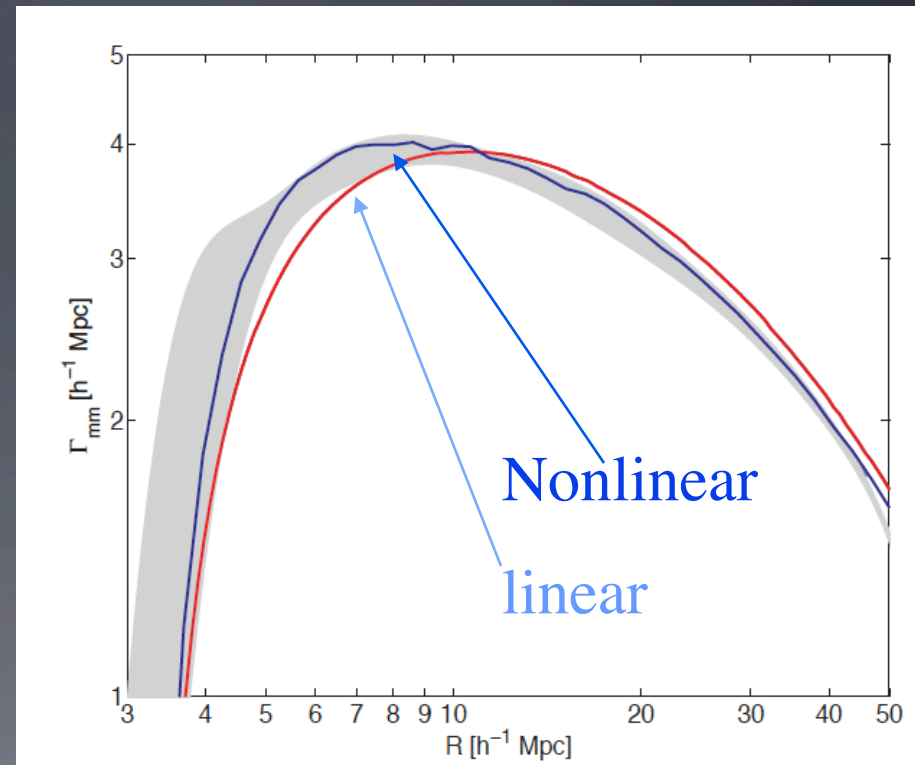
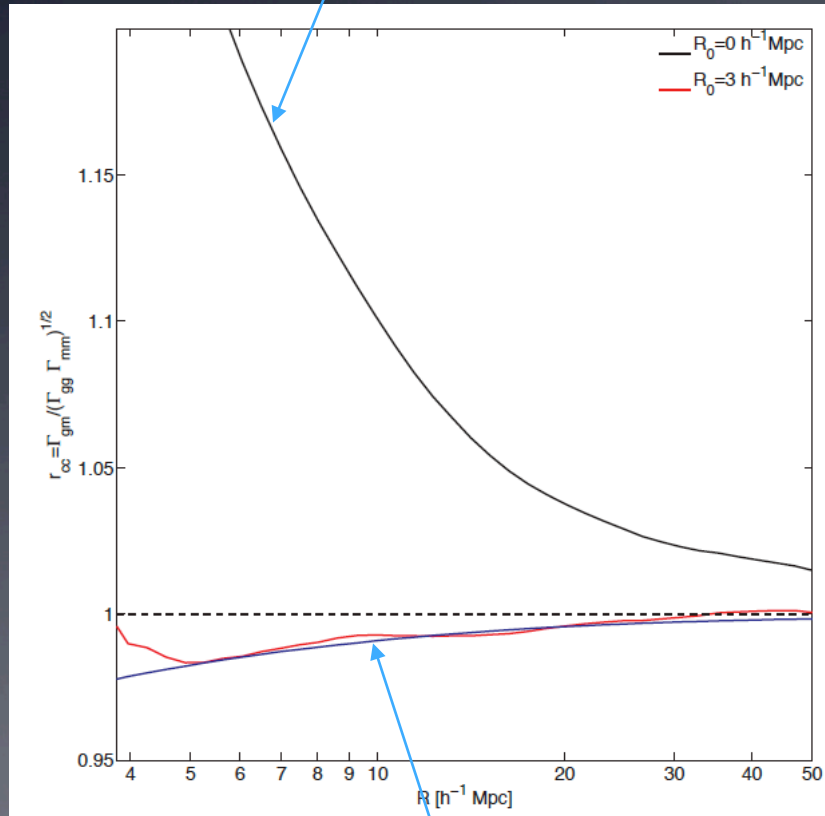


Simulations: dark matter reconstruction

Baldauf, Smith, US, Mandelbaum (2009)

Old statistic

$$r = \frac{\xi_{hm}}{\sqrt{\xi_{hh}\xi_{mm}}} \rightarrow \xi_{mm} = \frac{\xi_{hm}^2}{r^2\xi_{hh}}$$



New statistic: Cross-correlation coefficient r nearly unity

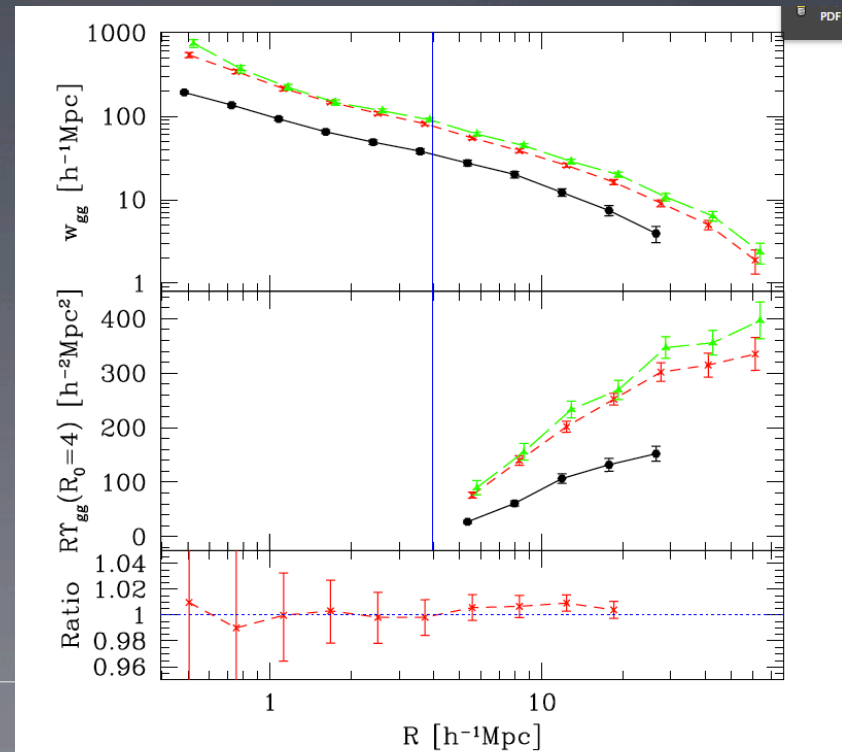
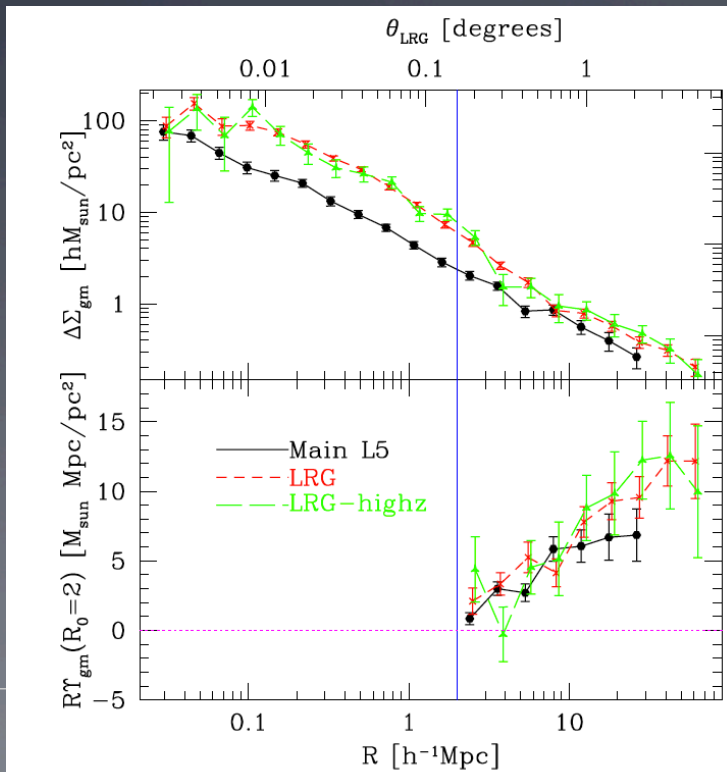
SDSS DR-7 data analysis Mandelbaum et al, 2012

LENSES

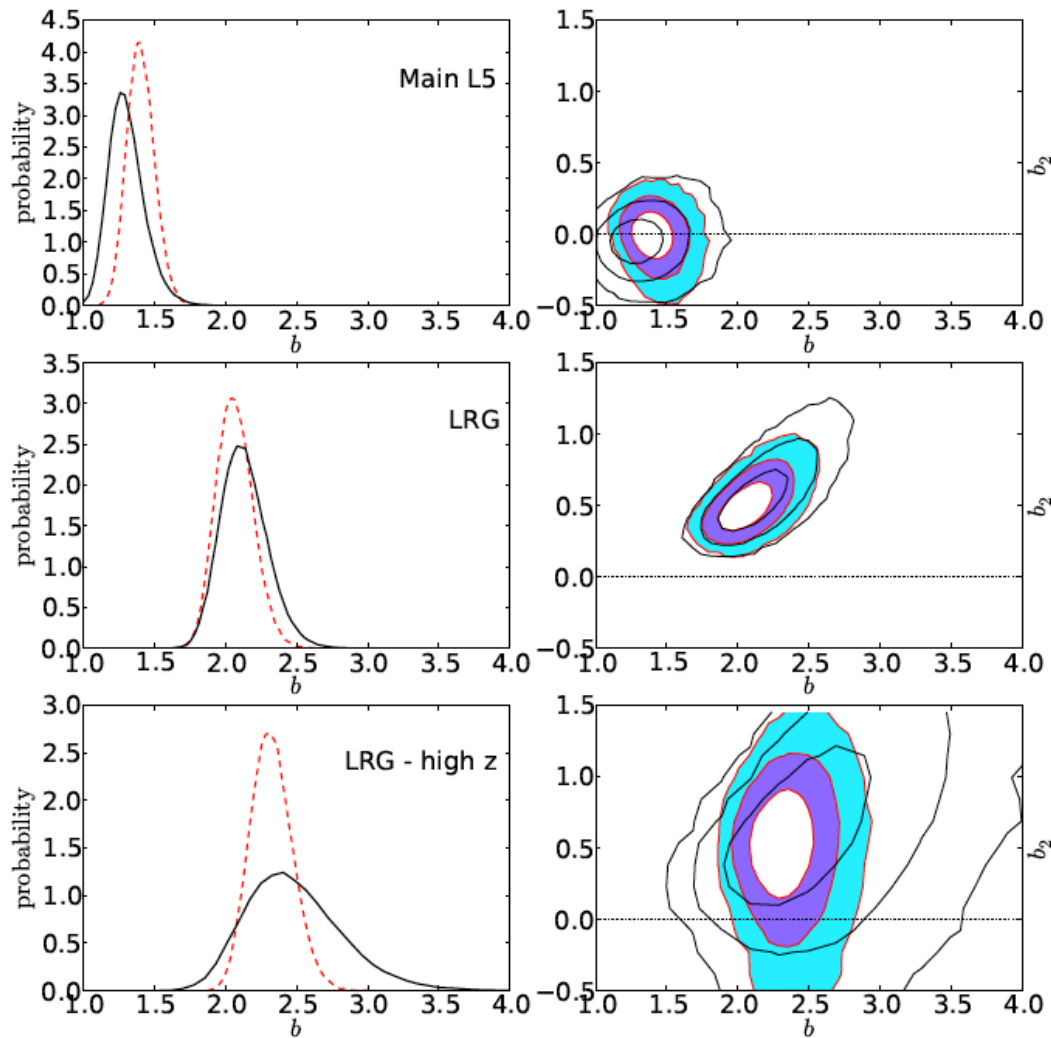
70,000 M^*-1 galaxies ($z < 0.15$),
62,000 low z LRGs ($0.16 < z < 0.3$),
35,000 high z LRGs ($0.36 < z < 0.47$)

SOURCES

10M, well calibrated photozs
using spectroscopic surveys

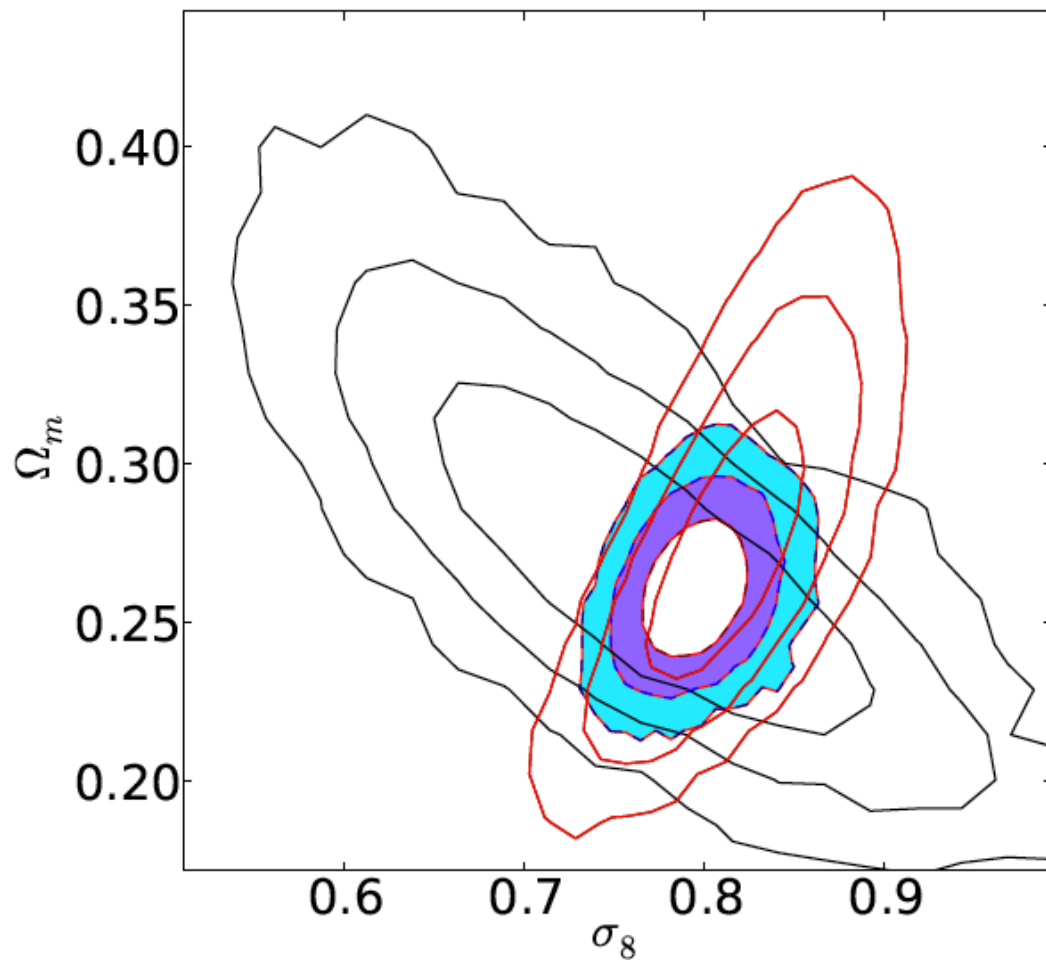


First direct detection of scale dependent bias



Cosmology constraints

$$\sigma_8 (\Omega_m / 0.25)^{0.57} = 0.795 \pm 0.048$$



SDSS

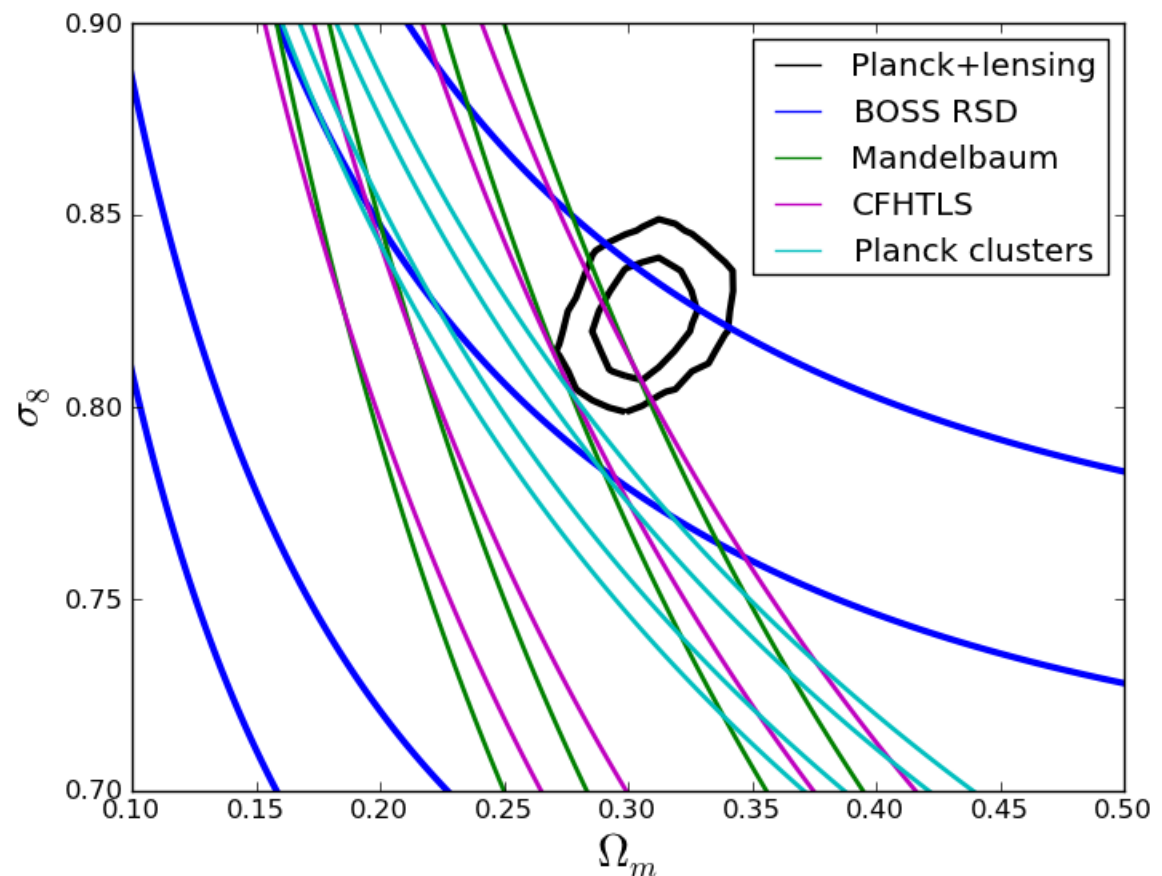
WMAP

Current LSS constraints: Planck (lensing) versus the rest of LSS

All LSS constraints (RSD, lensing, clusters) consistent

All to the left of Planck (prefer lower $\sigma_8 \Omega_m^x$)

How to resolve this?
With new data!

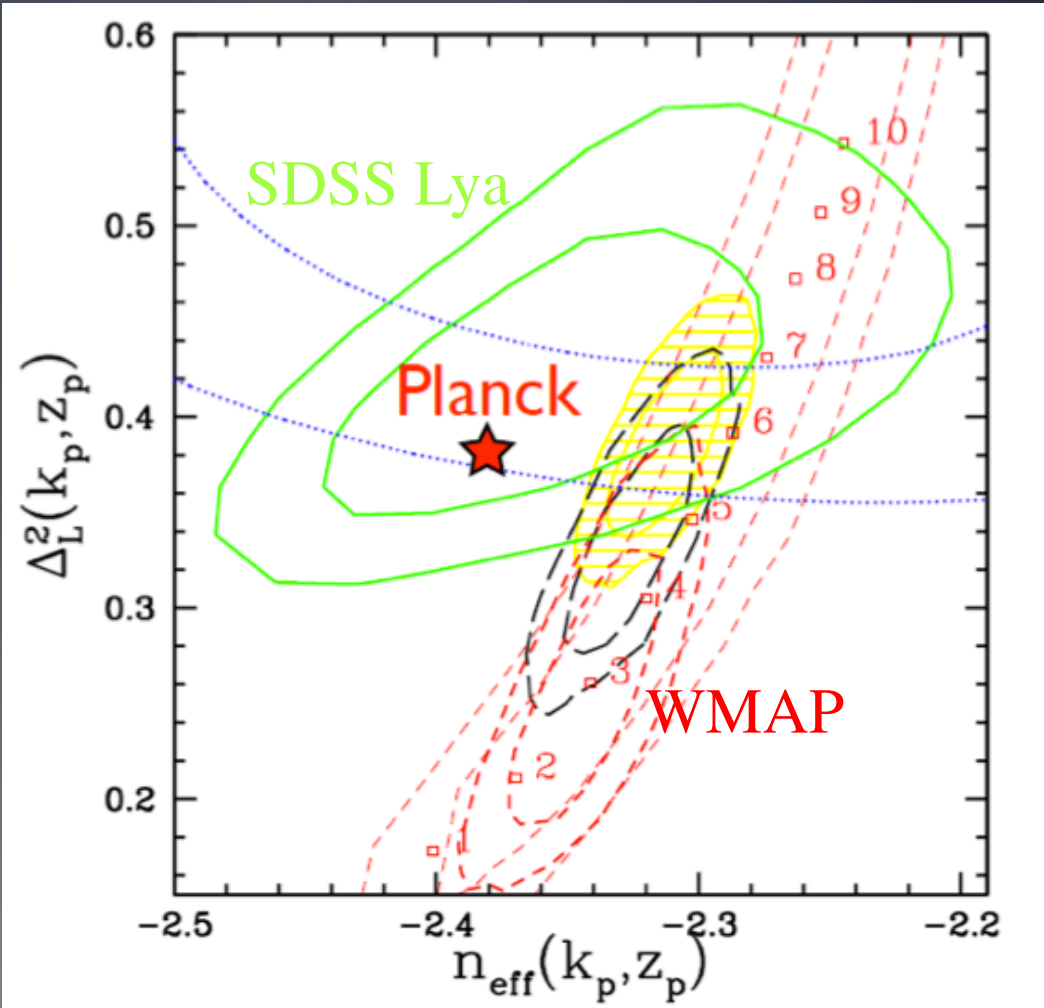


Small scale LSS: Lya forest 2005

In 2005 SDSS Lya forest power spectrum (McDonald et al) amplitude was higher than WMAP 3 year:

$$\sum m_\nu < 0.17\text{eV at } 2\sigma$$

With Planck this bound is weakened, but Lya is now in a better agreement with CMB



Halo-shear versus shear-shear lensing

shear-shear

galaxy-shear



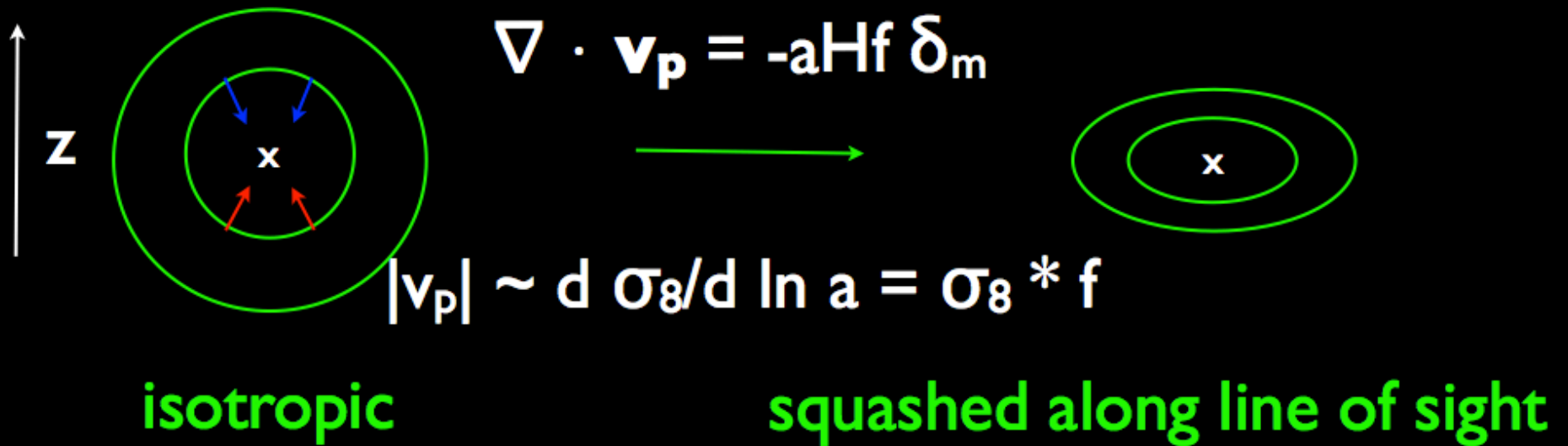
- Calibration bias: - -
- Intrinsic alignments - +
- Photoz induced error - -
- Instrument/sky induced correlations: - +
- Baryonic effects: - +

Lessons from last decade: shear-shear is difficult, galaxy-shear has fewer systematic uncertainties, complementary to shear-shear analysis

Redshift space distortions

redshift $cz = aHr + v_p$

real to redshift space separations



$$f = d \ln \sigma_8 / d \ln a$$

Reid

Linear and nonlinear effects

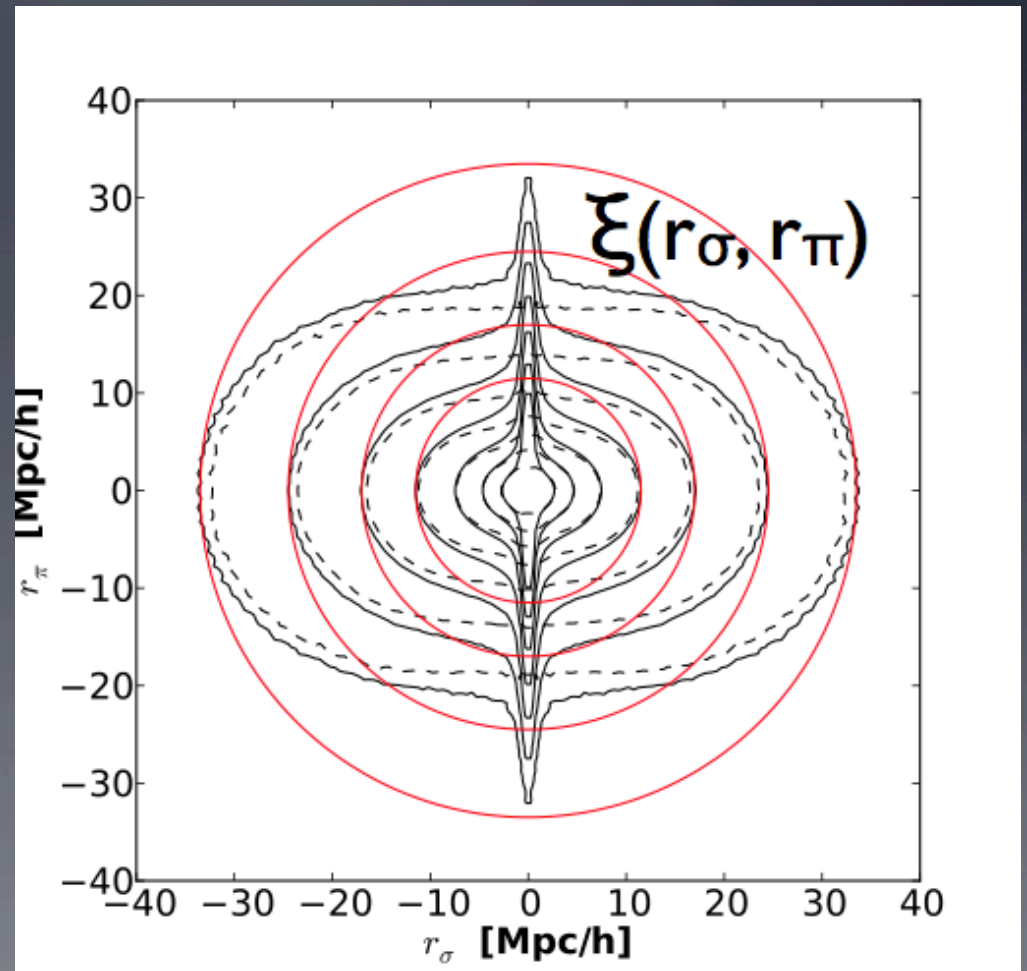
On very large scales linear RSD distortions:

$$\delta_g = (b + f\mu^2)\delta = b(1 + \beta\mu^2)\delta$$

$$\mu = \vec{k} \cdot \vec{n} / k \quad \beta = f/b$$

From angular dependence ($l=0,2$) we can determine $f\sigma_8$

On small scales: virialized velocities within halos lead to FoG, extending radially 10 times farther than transverse



Velocities are probed at galaxy positions: density weighted velocity moments

US, McDonald 2011

Lowest moments:
density, momentum
density, stress
energy density

RSD never directly
probe velocity, only
momentum
density...

$$\begin{aligned}\rho_s(\mathbf{k}) &= ma^{-3} \int d^3x d^3q f(\mathbf{x}, \mathbf{q}) e^{(i\mathbf{k}\cdot\mathbf{x} + ik_{\parallel} u_{\parallel} / \mathcal{H})} \\ &= ma^{-3} \int d^3x e^{i\mathbf{k}\cdot\mathbf{x}} \int d^3q f(\mathbf{x}, \mathbf{q}) e^{ik_{\parallel} u_{\parallel} / \mathcal{H}},\end{aligned}$$

$$\delta_s(\mathbf{k}) = \sum_{L=0} \frac{1}{L!} \left(\frac{ik_{\parallel}}{H} \right)^L T_{\parallel}^L(\mathbf{k}),$$

where $T_{\parallel}^L(\mathbf{k})$ is the Fourier transform of $T_{\parallel}^L(\mathbf{x})$.

$$T_{\parallel}^L(\mathbf{k}) = \int d^3\mathbf{x} T_{\parallel}^L(\mathbf{x}) e^{i\mathbf{k}\cdot\mathbf{x}}.$$

$$T_{\parallel}^L(\mathbf{x}) = \frac{m}{\bar{\rho}} \int d^3\mathbf{q} f(\mathbf{x}, \mathbf{q}) u_{\parallel}^L = \left\langle (1 + \delta(\mathbf{x})) u_{\parallel}^L(\mathbf{x}) \right\rangle_{\mathbf{x}}$$

RSD modeling

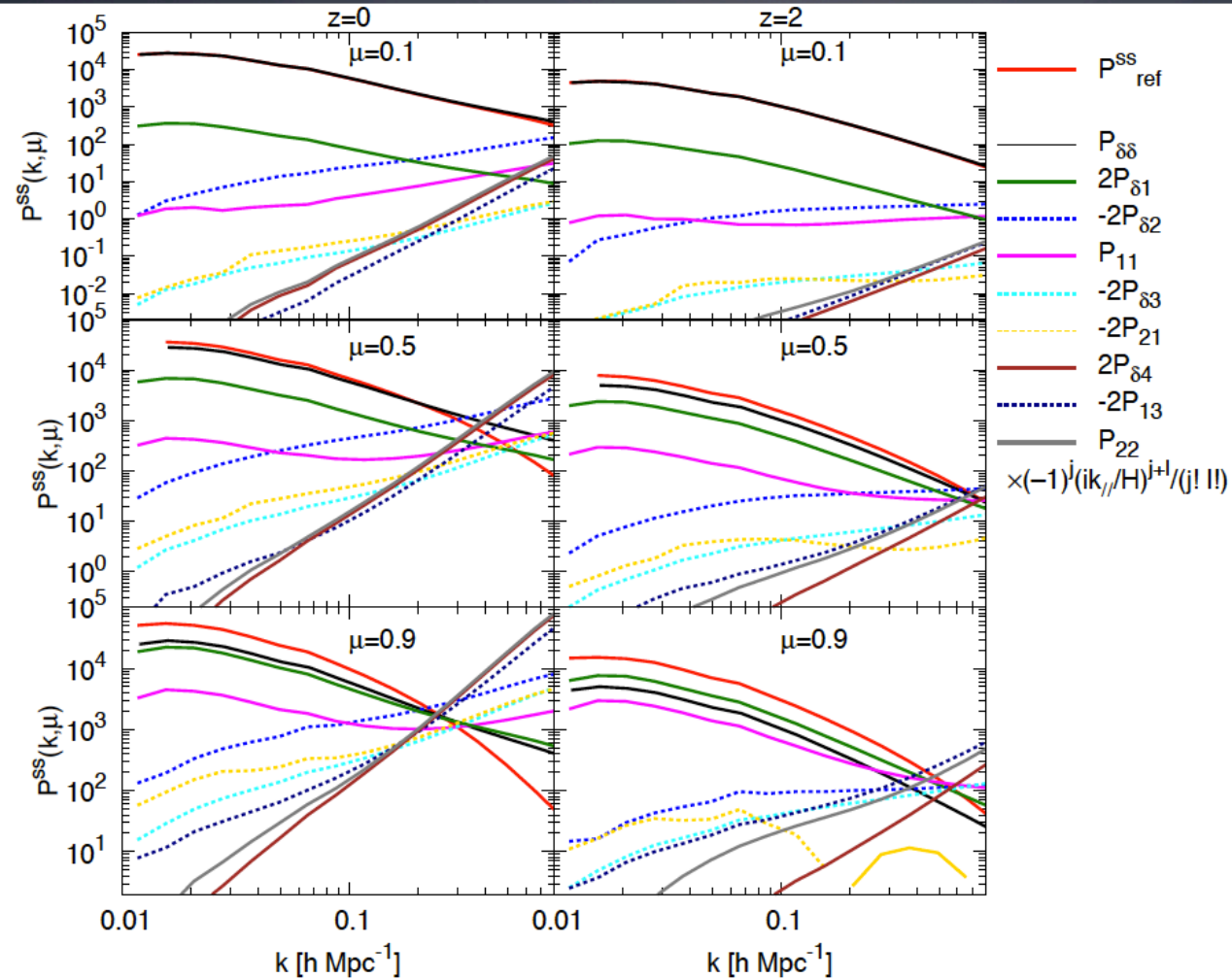
US & McDonald 2011

- Velocities are weighted by galaxy density: all biasing issues
- Not just momentum, but all velocity moments, weighted by galaxy density
- Need to compute all correlators allowed by symmetries

$$P^{ss}(\mathbf{k}) = \sum_{L=0}^{\infty} \frac{1}{L!^2} \left(\frac{k\mu}{H} \right)^{2L} P_{LL}(\mathbf{k}) + 2\text{Re} \sum_{L=0}^{\infty} \sum_{L'>L} \frac{(-1)^{L'}}{L! L'!} \left(\frac{ik\mu}{H} \right)^{L+L'} P_{LL'}(\mathbf{k})$$

- Series convergent if $k\nu\mu < 1$: breaks down at $k\mu = 0.2h/\text{Mpc} / (1+z)$

Simulations



Series convergent for $k\mu < 0.2h/\text{Mpc}/(1+z)$

Perturbation Theory approach

Vlah et al 2013

- SPT relative to dark matter :

$$P_{o1}^{gg} = \langle \delta_g | (1 + \delta_g) v_{||} \rangle = \langle (b_1 \delta_m + ((1 + b_1 \delta_m + b_2 \delta_m^2 + \dots) v_{||}) \rangle =$$

$$b_1 \langle \delta_m | (1 + \delta_m) v_{||} \rangle + \langle (b_1 \delta_m + b_2 \delta_m^2 + \dots) | (b_1 - 1) \delta_m + b_2 \delta_m^2 + \dots \rangle v_{||} =$$

$$b_1 P_{o1}^{mm} + \langle (b_1 \delta_m | (b_1 - 1) \delta_m v_{||} \rangle + \dots$$

We see we get scale dependent bias in P_{o1}^{gg} even with just scale independent bias b_1

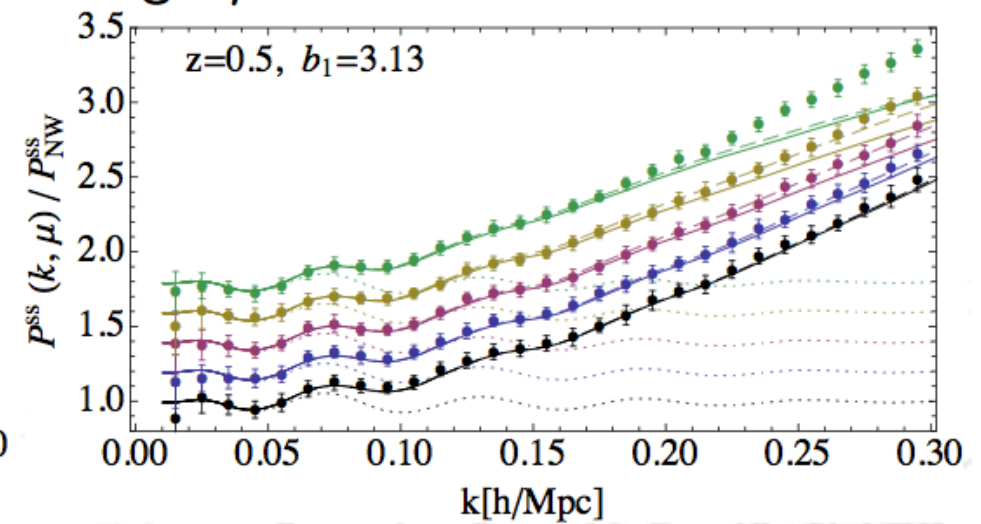
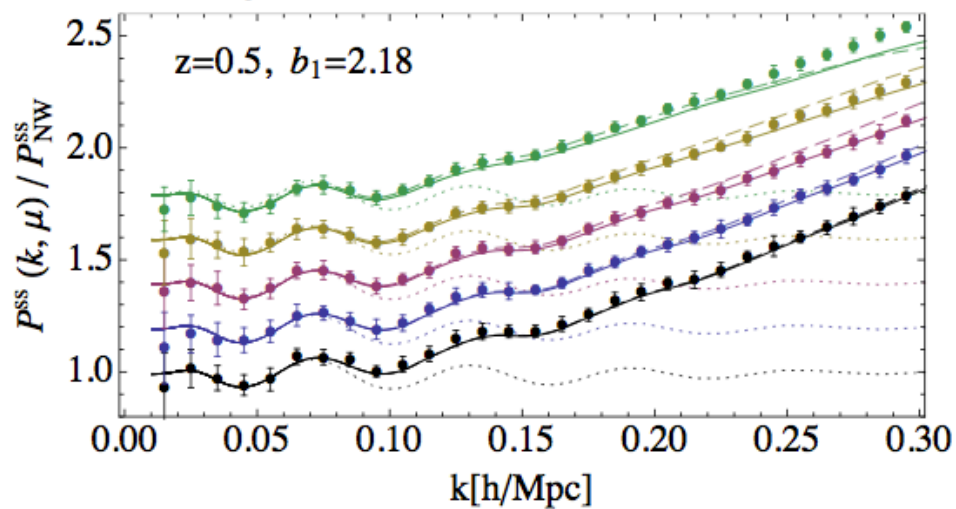
SPT captures some of these effects despite being problematic in terms of loop integrals

See other approaches by Taruya et al, Reid & White...

Current modeling status using PT

Vlah et al 2013

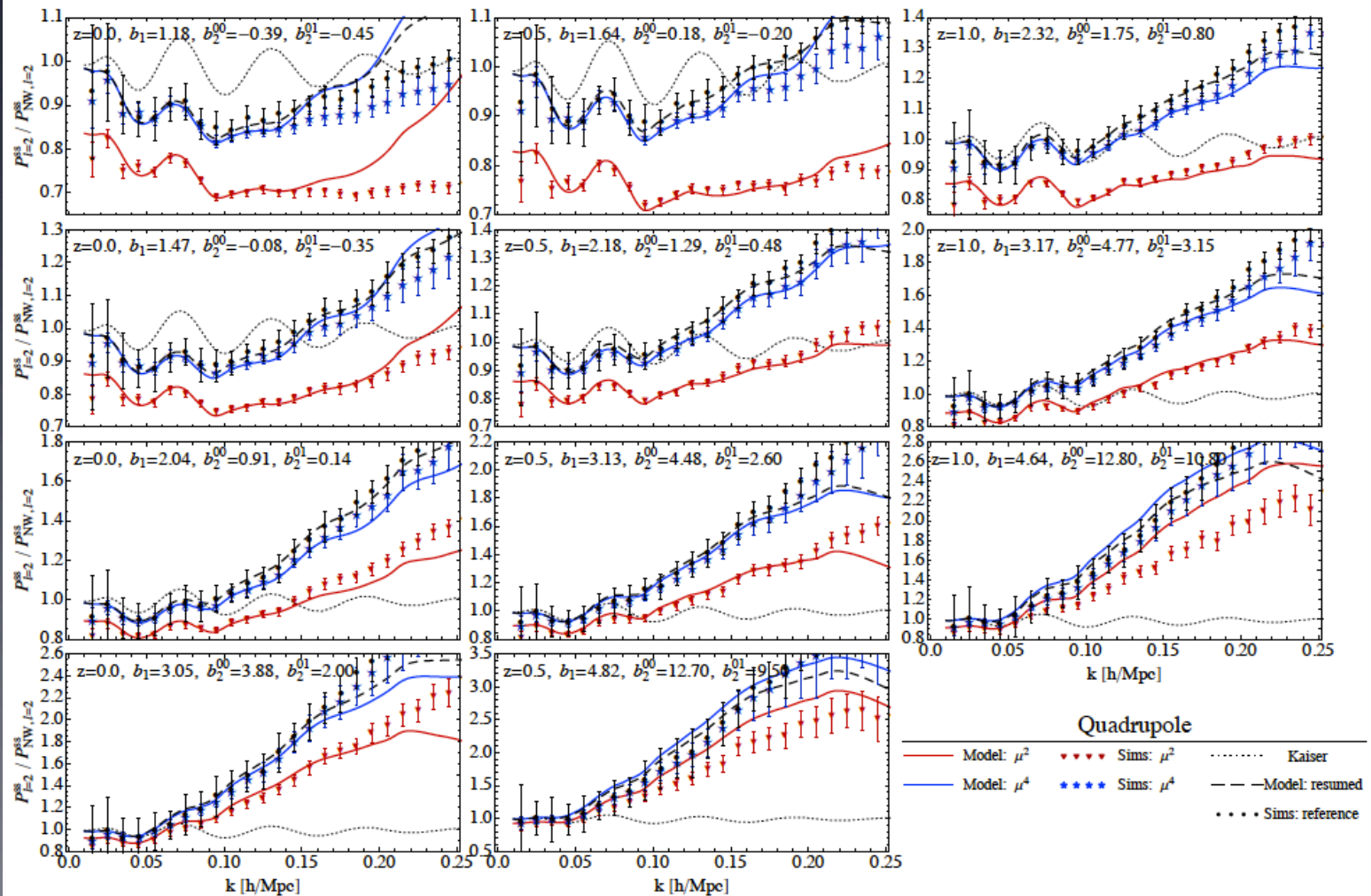
Power spectrum as a function of k and angle μ :



Models include 2 free nonlinear bias parameters b_2, b_3^{nl}

Current modeling status using PT: $l=2$

Note strong deviations from linear Kaiser at $k < 0.1 h/\text{Mpc}$



This is for halos, FoG yet another complication

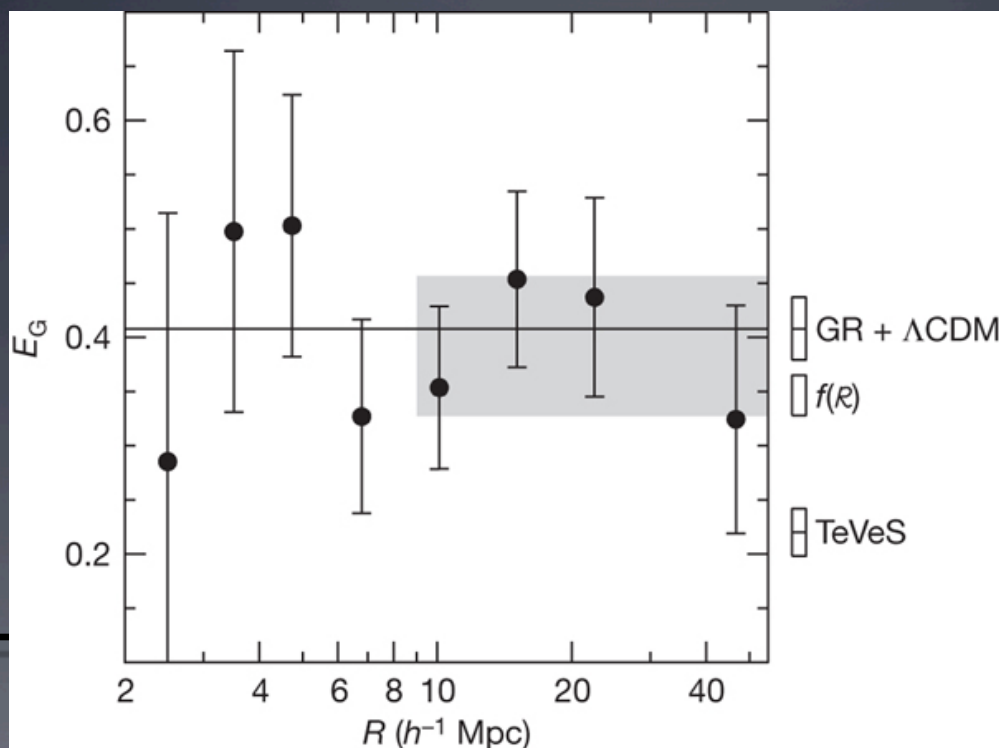
Combining galaxy-shear and RSD

- By combining redshift space distortion measurements ($b f \sigma_8$) with galaxy shear measurements ($b \Omega_m \sigma_8$) of the SAME objects we can eliminate the dependence on the amplitude of fluctuations σ_8 and bias b

$$E_G(R) = \frac{\Delta \Sigma_{gm}}{\beta \Delta \Sigma_{gg}} = \frac{\Omega_{m0}}{f}$$

Zhang et al 2007

Comparison of observational constraints with predictions from general relativity and viable modified theories of gravity.



R Reyes *et al.* *Nature* **464**, 256-258 (2010) doi:10.1038/nature08857

This was a 6 sigma detection, with BOSS/SDSS-III
we will do it at 25 sigma

nature

Conclusions

- Galaxy-shear lensing is a powerful alternative to shear-shear lensing, with fewer systematics, current SDSS-II constraints give some of the best WL constraints,
- CMB lensing is powerful: none of current LSS probes is competitive with Planck lensing, but combined they show tension with Planck lensing. New SDSS-III data will be competitive with Planck lensing. New SPT lensing data will test Planck lensing.
- Galaxy biasing is complicated, but if we can understand the different effects we may develop models that have no free parameters
- 3-d galaxy surveys have enormous statistical power, but because velocities are sampled at galaxy positions RSD are subject to biasing effects: PT models are successful in modeling nonlinear RSD effects for $k < 0.15h/\text{Mpc}$
- Combining lensing and RSD is a powerful way to test modified gravity