### 1.8 Lorentz transformations

We have an event at point P which is $x, y, z, t$ in frame S and $x^{\prime}, y^{\prime}, z^{\prime}, t^{\prime}$ in frame $S^{\prime}$. who do we relate these coordinates to each other if the origins $O-O^{\prime}$ are co-incident at $t=t^{\prime}=0$ where $S^{\prime}$ moves relative to $S$ in the +ve x direction at speed $u$.

Lets make it more clear. The distance $\mathrm{O}^{\prime}$ to P is $x^{\prime}=L^{\prime}$ is proper distance in $S^{\prime}$ This will be seen in $S$ as length contracted to $L=L^{\prime} / \gamma=$ $x^{\prime} / \gamma$
hence the distance O to P as measured in $S$ is the speed of the frame plus the length contracted distance measured in S i.e.
$x=u t+L=u t+x^{\prime} / \gamma$
solve for $x^{\prime}$ and get
$x^{\prime}=\gamma(x-u t)$
and then we can just write down what happens for $S^{\prime}$ to $S$ (swap $u$ for -u and primes for unprimes but REMEMBER time
37.15 As measured in frame of reference $S, x^{\prime}$ is contracted to $x^{\prime} / \gamma$, so $x=u t+x^{\prime} / \gamma$ and $x^{\prime}=\gamma(x-u t)$.

Frame $S^{\prime}$ moves relative to frame $S$ with constant velocity $u$ along the common $x$ - $x^{\prime}$-axis.


The Lorentz coordinate transformation relates the spacetime coordinates of an event as measured in the two frames: $(x, y, z, t)$ in frame $S$ and $\left(x^{\prime}, y^{\prime}, z^{\prime}, t^{\prime}\right)$ in frame $S^{\prime}$.

Figure 5:
so start at the same place as before but swap to get $x^{\prime}=-u t^{\prime}+x / \gamma$
so we have two equations for $x^{\prime}$ so we can eliminate and solve to get how $t$ relates to $t^{\prime}$

$$
\begin{aligned}
& -u t^{\prime}+x / \gamma=\gamma x-\gamma u t \\
& -\gamma u t^{\prime}+x=\gamma^{2} x-\gamma^{2} u t \\
& \gamma u t^{\prime}=x\left(1-\gamma^{2}\right)+\gamma^{2} u t
\end{aligned}
$$

but we have $1-\gamma^{2}=1-1 /\left(1-\beta^{2}\right)=\left(1-\beta^{2}-1\right) /\left(1-\beta^{2}\right)=-\beta^{2} \gamma^{2}$ so

$$
\begin{aligned}
\gamma u t^{\prime} & =\gamma^{2} u t-\beta^{2} \gamma^{2} x \\
t^{\prime} & =\gamma\left(t-x u / c^{2}\right)
\end{aligned}
$$

bring everything together and we have the Lorentz transformations

$$
x^{\prime}=\gamma(x-u t) \quad y^{\prime}=y \quad z^{\prime}=z \quad t^{\prime}=\gamma\left(t-x u / c^{2}\right)
$$

or we can write these for quantities in $S$ given those in $S^{\prime}$ as (replace $-u$ or $u$ and swap primed/unprimed)

$$
x=\gamma\left(x^{\prime}+u t^{\prime}\right) \quad y=y^{\prime} \quad z=z^{\prime} \quad t=\gamma\left(t^{\prime}+x^{\prime} u / c^{2}\right)
$$

For values of $u \ll c$ then $\gamma(u) \rightarrow 1$ and we get back to the galilean transformations of classical mechanics. but for $u \rightarrow c$ then space and time become intertwined and we can no longer say that they are absolutes independent of the frame of reference. The only SPECIAL frame of reference is the rest frame.
the combination $x, y, z, t$ is called the spacetime coordinates of an event as measured in S. They relate to spacetime coordinates in frame $S^{\prime}$ via these transformations.

Example YF37.6. Mavis pilots her spacecraft across a finish line at 0.6 c relative to the line, winning the race. (event 1). according to her, at the same instant as she, at the front of the ship, sees herself crossing the line, a 'hooray' message is sent from the back of the ship (event 2). She measures the length of her ship to be 300 m . stanley is at the finish line, and is at rest relative to it. when and where does he measure events 1 and 2

Set up in the standard way. Mavis is in $S^{\prime}$ as here she is at rest relative to the ship. let the origins coincide at $t=t^{\prime}=0$ when mavis crosses the line. then event 1 in $S^{\prime}$ is at $x_{1}^{\prime}, y_{1}^{\prime}, z_{1}^{\prime}, t_{1}^{\prime}=0,0,0,0$ event 2 in $S^{\prime}$ is at $-300,0,0,0$ as the events are instantaneous in this frame and the ships length is 300 m in this frame.

First job is ALWAYS calculate $\gamma=1 / \sqrt{1-\beta^{2}}=1 / \sqrt{\left(1-0.6^{2}\right)}=1.25$
in $S$ event 1 is at $x_{1}=\gamma\left(x_{1}^{\prime}+u t_{1}\right)=0$ and $t_{1}=t_{1}^{\prime}=0$
in S , event 2 is as $x_{2}=\gamma\left(x_{2}^{\prime}+u t_{2}\right)=1.25 \times-300=-375 \mathrm{~m}$ and is seen at time $t_{2}=\gamma\left(t_{2}^{\prime}+x_{2}^{\prime} u / c^{2}\right)=1.25 \times\left(0-300 \times 0.6 / c=-225 / c=-7.5 \times 10^{-7} s\right.$
its -ve!! so in S , the hooray message comes $0.75 \mu$ s BEFORE SHE HAS WON!!
but its not violating causality!! mavis DOES NOT TRIGGER THE SIGNAL FROM THE BACK OF THE SPACECRAFT. if she had, it would add an extra time $300 / c=1 \times 10^{-6}$ s to get from the front to the back of the spacecraft. Hence event 2 in her frame $S^{\prime}$ has coordinates $-300,0,0,10^{-6}$ and then stanley measures event 2 happening at time $t_{2}=\gamma\left(t_{2}^{\prime}+x_{2}^{\prime} u / c^{2}\right)=$ $1.25 \times\left(10^{-6}-300 \times 0.6 / c\right)=5 \times 10^{-7} s$
this is now +ve , so causality is actually preserved!
causality is what we care about because its about PHYSICS. Simulteneity is just a question of the observers point of view - observers can disagree about whether an object behind me is seen directly in line with me or projected to my left or my right. its not an important difference, everyones view is 'correct'. but if I am HOLDING the object (so I can affect it physically) then all observers agree that its in line with me.

### 1.9 Lorentz velocity transformations

we had the lorentz transformations between coordinates

$$
x^{\prime}=\gamma(x-u t) \quad y^{\prime}=y \quad z^{\prime}=z \quad t^{\prime}=\gamma\left(t-x u / c^{2}\right)
$$

but we can re-write them considering only a small displacement $d x, d y, d z, d t$ and get

$$
\begin{gathered}
d x^{\prime}=\gamma(d x-u d t) \quad d y^{\prime}=d y \quad d z^{\prime}=d z \quad d t^{\prime}=\gamma\left(d t-d x u / c^{2}\right) \\
d x^{\prime} / d t^{\prime}=\gamma(d x-u d t) / \gamma\left(d t-d x u / c^{2}\right) \\
=\frac{d x / d t-u}{1-d x / d t u / c^{2}} \\
v_{x}^{\prime}=\frac{v_{x}-u}{1-v_{x} u / c^{2}}
\end{gathered}
$$

This has some interesting properties! when $u, v_{x} \ll c$ then $v_{x}^{\prime} \rightarrow v_{x}-u$ as expected. but when we go to $v_{x} \rightarrow c$ then $v_{x}^{\prime} \rightarrow c$ also - lets see this explicitly by setting $v_{x}=c$

$$
v_{x}^{\prime}=\frac{c-u}{1-c u / c^{2}}=c \frac{c-u}{c-u}=c
$$

this says that anything moving with velocity $\rightarrow c$ in S also has velocity $v_{x}^{\prime} \rightarrow c$ in S' despite the relative notion of the two frames. so th espeed of light is the same in any frame (by construction!!)
37.16 The spaceship, robot space probe, and scoutship.


Figure 6:

We get the inverse transforms as ever by swapping primes and unprimes and $-u$ for $u$.

$$
v_{x}=\frac{v_{x}^{\prime}+u}{1+u v_{x}^{\prime} / c^{2}}
$$

Example YF37.7 spacecraft moving away from earth at 0.9c fires robot space probe in same directon as its motion at 0.7 c as seen from the spacecraft. what is the velocity as seen from the earth?
so spacecraft is $S^{\prime}$, and its velocity relative to earth in $S$ is $u=0.9 c$.
robot has $v_{x}^{\prime}=0.7 c$ as its relative to the spacecraft
this would be seen in $S$ as $v_{x}=\frac{0.7 c+0.9 c}{1+0.7 \times 0.9}=0.982 c$
a scoutship is sent from earth at 0.95 c to try to catch up with the spacecraft What is the speed of the spacecraft with respect to the scout?
we want to measure the scout velocity relative to the spacecraft so we so want the spacecraft to be $S$ ' as then we'd be calculating directly in its rest frame. so then $\mathrm{u}=0.9 \mathrm{c}$. then in the earth frame S we have $v_{x}=0.95 c$ for the scout. so we can calculate $v_{x}^{\prime}$ as

$$
v_{x}^{\prime}=\frac{v_{x}-u}{1-u v_{x} / c^{2}}=c \frac{0.95-0.9}{1-0.9 \times 0.95}=0.345 c
$$

so the scout is catching up with the spacecraft (as expected as its going at 0.95 c relative to the earth whereas the spacecraft is only going at 0.9 c ).
now lets think instead about the velocity of the scout relative to the robot. so we want the robot frame to be $S^{\prime}$, so this is moving at velocity $u=0.982 \mathrm{c}$ in the earth frame. so the robot isn't going to get caught as it has $v_{x}=0.95 \mathrm{c}$ in the earth frame. lets see this explicitly.

$$
v_{x}^{\prime}=\frac{v_{x}-u}{1-u v_{x} / c^{2}}=c \frac{0.95-0.982}{1-0.95 \times 0.982}=-0.477 c
$$

